6ES7511-1CK01-0AB0

Data sheet



SIMATIC S7-1500 Compact CPU CPU 1511C-1PN, central processing unit with working memory 175 KB for program and 1 MB for data, 16 digital inputs, 16 digital outputs, 5 analog inputs, 2 analog outputs, 6 high speed counters, 4 high speed outputs for PTO/PWM/frequency output 1. interface: PROFINET IRT with 2 port switch, 60 NS bit-performance, incl. front connector push-in, SIMATIC memory card necessary

General information	
Product type designation	CPU 1511C-1 PN
HW functional status	FS03
Firmware version	V2.9
Product function	
 I&M data 	Yes; I&M0 to I&M3
Isochronous mode	Yes; With minimum OB 6x cycle of 625 µs (distributed)
Engineering with	
 STEP 7 TIA Portal configurable/integrated from version 	V17 (FW V2.9) / V15 (FW V2.5) or higher; with older TIA Portal versions configurable as 6ES7511-1CK00-0AB0
Configuration control	
via dataset	Yes
Display	
Screen diagonal [cm]	3.45 cm
Control elements	
Number of keys	8
Mode buttons	2
Supply voltage	
Type of supply voltage	DC
Rated value (DC)	24 V
permissible range, lower limit (DC)	19.2 V; 20.4 V DC, for supplying the digital inputs/outputs
permissible range, upper limit (DC)	28.8 V
Reverse polarity protection	Yes
Mains buffering	
 Mains/voltage failure stored energy time 	5 ms; Refers to the power supply on the CPU section
Repeat rate, min.	1/s
Input current	
Current consumption (rated value)	0.8 A; Without load; 9.8 A: CPU + load
Current consumption, max.	1 A; Without load; 10 A: CPU + load
Inrush current, max.	1.9 A; Rated value
l²t	0.34 A ² ·s
Digital inputs	
• from load voltage L+ (without load), max.	20 mA; per group
Digital outputs	
from load voltage L+, max.	30 mA; Per group, without load
output voltage / header	
Rated value (DC)	24 V
Encoder supply	
Number of outputs	1; One common 24 V encoder supply

24 V encoder supply • 24 V • Short-circuit protection • Output current, max. Power Infeed power to the backplane bus Power consumption from the backplane bus (balanced) Power loss Power loss Power loss, typ. 11.8 W Memory Number of slots for SIMATIC memory card SIMATIC memory card required Work memory • integrated (for program) 175 kbyte	
Short-circuit protection Output current, max. Power Infeed power to the backplane bus Power consumption from the backplane bus (balanced) Power loss Power loss, typ. 11.8 W Memory Number of slots for SIMATIC memory card SIMATIC memory card required Work memory Work memory Yes 1 A 1 A 1 A Power 1 1 8 W Memory Number of slots for SIMATIC memory card SIMATIC memory card required Yes	
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Power loss Power loss, typ. 11.8 W Memory Number of slots for SIMATIC memory card 1 SIMATIC memory card required Yes Work memory	
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SIMATIC memory card required Yes Work memory	
Work memory	
·	
• integrated (for program) 175 kbyte	
3 - 3 - 7	
• integrated (for data) 1 Mbyte	
Load memory	
Plug-in (SIMATIC Memory Card), max. 32 Gbyte	
Backup	
• maintenance-free Yes	
CPU processing times	
for fixed point arithmetic, typ. 96 ns	
for floating point arithmetic, typ. 384 ns	
CPU-blocks	
Number of elements (total) 4 000; Blocks (OB, FB, FC	C, DB) and UDTs
DB	
	to: number range that can be used by the nber range of DBs created via SFC 86: 60 000
• Size, max. 1 Mbyte; For DBs with abs	solute addressing, the max. size is 64 KB
FB	
• Number range 0 65 535	
• Size, max. 175 kbyte	
FC	
• Number range 0 65 535	
• Size, max. 175 kbyte	
OB	
• Size, max. 175 kbyte	
Number of free cycle OBs	
Number of time alarm OBs 20	
Number of delay alarm OBs 20 20: With minimum OB 3v of a valid interrupt OBs 20: With minimum OB 3v of a valid interrupt OBs 20: With minimum OB 3v of a valid interrupt OBs	evels of 500 us
Number of cyclic interrupt OBs 20; With minimum OB 3x c	cycle of 500 µs
Number of process alarm OBs	
Number of DPV1 alarm OBs	
 Number of isochronous mode OBs 	
 Number of technology synchronous alarm OBs 	
Number of startup OBs	
 Number of asynchronous error OBs 	
Number of synchronous error OBs 2	
Number of diagnostic alarm OBs	
Nesting depth	
• per priority class 24	
Counters, timers and their retentivity	
S7 counter	
Number 2 048	
Detention	
Retentivity	
— adjustable Yes	
·	

Retentivity	
— adjustable	Yes
S7 times	
Number	2 048
Retentivity	
— adjustable	Yes
IEC timer	
Number	Any (only limited by the main memory)
Retentivity	ray (em) minou by the main memory
— adjustable	Yes
Data areas and their retentivity	
	120 khuta. In tatak availahla ratantiva mamaru far hit mamariaa timara
Retentive data area (incl. timers, counters, flags), max.	128 kbyte; In total; available retentive memory for bit memories, timers, counters, DBs, and technology data (axes): 88 KB
Extended retentive data area (incl. timers, counters, flags),	1 Mbyte; When using PS 6 0W 24/48/60 V DC HF
max.	
Flag	
• Size, max.	16 kbyte
Number of clock memories	8; 8 clock memory bit, grouped into one clock memory byte
Data blocks	
Retentivity adjustable	Yes
Retentivity preset	No
Local data	
per priority class, max.	64 kbyte; max. 16 KB per block
Address area	
Number of IO modules	1 024; max. number of modules / submodules
I/O address area	1 02 1, max. nambor of modules / casmodales
• Inputs	32 kbyte; All inputs are in the process image
Outputs	32 kbyte; All outputs are in the process image
per integrated IO subsystem	32 kbyte, All outputs are in the process image
— Inputs (volume)	8 kbyte
— Outputs (volume)	8 kbyte
per CM/CP	o kbyte
·	9 khuta
— Inputs (volume)	8 kbyte
— Outputs (volume)	8 kbyte
Subprocess images	22
Number of subprocess images, max.	32
Hardware configuration	
Number of distributed IO systems	32; A distributed I/O system is characterized not only by the integration of distributed I/O via PROFINET or PROFIBUS communication modules, but also by the connection of I/O via AS-i master modules or links (e.g. IE/PB-Link)
Number of DP masters	
• Via CM	4; A maximum of 4 CMs/CPs (PROFIBUS, PROFINET, Ethernet) can be inserted in total
Number of IO Controllers	
• integrated	1
Via CM	4; A maximum of 4 CMs/CPs (PROFIBUS, PROFINET, Ethernet) can
D 1	be inserted in total
Rack	00. ODIL + 04 dula-
Modules per rack, max.	32; CPU + 31 modules
Number of lines, max. PER CM	1
PtP CM	the number of connectable DtD ONA-is substituted to
Number of PtP CMs	the number of connectable PtP CMs is only limited by the number of available slots
Time of day	
Clock	
• Type	Hardware clock
Backup time	6 wk; At 40 °C ambient temperature, typically
Deviation per day, max.	10 s; Typ.: 2 s
Operating hours counter	
Number	16

Clark augstranization	
Clock synchronization	V.
• supported	Yes
• in AS, master	Yes
• in AS, slave	Yes
on Ethernet via NTP	Yes
Digital inputs	
integrated channels (DI)	16
Digital inputs, parameterizable	Yes
Source/sink input	P-reading
Input characteristic curve in accordance with IEC 61131, type 3	Yes
Digital input functions, parameterizable	
Gate start/stop	Yes
Capture	Yes
Synchronization	Yes
Input voltage	
Type of input voltage	DC
Rated value (DC)	24 V
• for signal "0"	-3 to +5V
• for signal "1"	+11 to +30V
Input current	-11 10 1001
·	2.5 mg A
• for signal "1", typ.	2.5 mA
Input delay (for rated value of input voltage)	
for standard inputs	
— parameterizable	Yes; none / 0.05 / 0.1 / 0.4 / 1.6 / 3.2 / 12.8 / 20 ms
— at "0" to "1", min.	4 μs; for parameterization "none"
— at "0" to "1", max.	20 ms
— at "1" to "0", min.	4 μs; for parameterization "none"
— at "1" to "0", max.	20 ms
for interrupt inputs	
— parameterizable	Yes; Same as for standard inputs
for technological functions	
— parameterizable	Yes; Same as for standard inputs
Cable length	
• shielded, max.	1 000 m; 600 m for technological functions; depending on input frequency, encoder and cable quality; max. 50 m at 100 kHz
unshielded, max.	600 m; for technological functions: No
Digital outputs	
Type of digital output	Transistor
integrated channels (DO)	16
Current-sourcing	Yes; Push-pull output
Short-circuit protection	Yes; electronic/thermal
Response threshold, typ.	1.6 A with standard output, 0.5 A with high-speed output; see manual for
Tresponse unesticia, typ.	details
Limitation of inductive shutdown voltage to	-0.8 V
Controlling a digital input	Yes
Accuracy of pulse duration	Up to ±100 ppm ±2 µs at high-speed output; see manual for details
minimum pulse duration	2 µs; With High Speed output
Digital output functions, parameterizable	_ p-,g opost output
Switching tripped by comparison values	Yes; As output signal of a high-speed counter
PWM output	Yes
— Number, max.	4
Cycle duration, parameterizable	Yes
— ON period, min.	0 %
— ON period, max.	100 %
 Resolution of the duty cycle 	0.0036 %; For S7 analog format, min. 40 ns
Frequency output	Yes
Switching capacity of the outputs	
Switching capacity of the outputs • with resistive load, max.	0.5 A; 0.1 A with high-speed output, i.e. when using a high-speed output; see manual for details

	see manual for details
Load resistance range	
• lower limit	48 Ω ; 240 ohms with high-speed output, i.e. when using a high-speed
	output; see manual for details
• upper limit	12 kΩ
Output voltage	DO.
Type of output voltage	DC
• for signal "0", max.	1 V; With high-speed output, i.e. when using a high-speed output; see manual for details
• for signal "1", min.	23.2 V; L+ (-0.8 V)
Output current	20.2 V, 2 (0.0 V)
for signal "1" rated value	0.5 A; 0.1 A with high-speed output, i.e. when using a high-speed
•	output, observe derating; see manual for details
for signal "1" permissible range, min.	2 mA
for signal "1" permissible range, max.	0.6 A; 0.12 A with high-speed output, i.e. when using a high-speed
- for circul IIOII recidual current recy	output, observe derating; see manual for details
• for signal "0" residual current, max.	0.5 mA
Output delay with resistive load	200 μο
"0" to "1", max."1" to "0", max.	200 µs 500 µs; Load-dependent
for technological functions	ουο μο, Load-dependent
— "0" to "1", max.	5 μs; Depending on the output used, see additional description in
— 0 to 1, max.	manual
— "1" to "0", max.	5 μs; Depending on the output used, see additional description in
	manual
Parallel switching of two outputs	
for logic links	Yes; for technological functions: No
for uprating	No
for redundant control of a load	Yes; for technological functions: No
Switching frequency	
with resistive load, max.	100 kHz; For high-speed output, 100 Hz for standard output
with inductive load, max.	0.5 Hz; Acc. to IEC 60947-5-1, DC-13; observe derating curve
• on lamp load, max.	10 Hz
Total current of the outputs	
Current per channel, max.	0.5 A; see additional description in the manual 8 A; see additional description in the manual
Current per group, max. Current per power supply max.	4 A; 2 power supplies for each group, current per power supply max. 4
 Current per power supply, max. 	A, see additional description in manual
for technological functions	
— Current per channel, max.	0.5 A; see additional description in the manual
Relay outputs	
Number of relay outputs	0
Cable length	
shielded, max.	1 000 m; 600 m for technological functions; depending on output
	frequency, load, and cable quality; max. 50 m at 100 kHz
• unshielded, max.	600 m; for technological functions: No
Analog inputs	
Number of analog inputs	5; 4x for U/I, 1x for R/RTD
For current measurement	4; max.
For voltage measurement	4; max.
 For resistance/resistance thermometer measurement 	1
permissible input voltage for voltage input (destruction	28.8 V
limit), max.	20.0 V
permissible input current for current input (destruction limit), max.	40 mA
Cycle time (all channels), min.	1 ms; Dependent on the parameterized interference frequency suppression; for details, see conversion procedure in manual
Technical unit for temperature measurement adjustable	Yes; °C/°F/K
Input ranges (rated values), voltages	
IIIbut failues trated values). Voltades	
• 0 to +10 V	Yes: Physical measuring range: ± 10 V
	Yes; Physical measuring range: \pm 10 V 100 k Ω

— Input resistance (1 V to 5 V)	100 kΩ
- Input resistance (1 v to 5 v) • -10 V to +10 V	Yes
— Input resistance (-10 V to +10 V)	100 kΩ
• -5 V to +5 V	Yes; Physical measuring range: ± 10 V
— Input resistance (-5 V to +5 V)	100 k Ω
Input ranges (rated values), currents	100 102
• 0 to 20 mA	Yes; Physical measuring range: ± 20 mA
— Input resistance (0 to 20 mA)	50 Ω; Plus approx. 55 ohm for overvoltage protection by PTC
• -20 mA to +20 mA	Yes
— Input resistance (-20 mA to +20 mA)	50 Ω; Plus approx. 55 ohm for overvoltage protection by PTC
• 4 mA to 20 mA	Yes; Physical measuring range: ± 20 mA
— Input resistance (4 mA to 20 mA)	50 Ω; Plus approx. 55 ohm for overvoltage protection by PTC
Input ranges (rated values), resistance thermometer	
• Ni 100	Yes; Standard/climate
— Input resistance (Ni 100)	10 ΜΩ
• Pt 100	Yes; Standard/climate
— Input resistance (Pt 100)	10 ΜΩ
Input ranges (rated values), resistors	
• 0 to 150 ohms	Yes; Physical measuring range: 0 600 ohms
— Input resistance (0 to 150 ohms)	10 ΜΩ
• 0 to 300 ohms	Yes; Physical measuring range: 0 600 ohms
— Input resistance (0 to 300 ohms)	10 ΜΩ
• 0 to 600 ohms	Yes
— Input resistance (0 to 600 ohms)	10 ΜΩ
Cable length	
• shielded, max.	800 m; for U/I, 200 m for R/RTD
Analog outputs	
integrated channels (AO)	2
Voltage output, short-circuit protection	Yes
Cycle time (all channels), min.	1 ms; Dependent on the parameterized interference frequency suppression; for details, see conversion procedure in manual
Output ranges, voltage	suppression, for details, see sometiment procedure in mandal
• 0 to 10 V	Yes
• 1 V to 5 V	Yes
• -10 V to +10 V	Yes
Output ranges, current	
• 0 to 20 mA	Yes
• -20 mA to +20 mA	Yes
• 4 mA to 20 mA	Yes
Load impedance (in rated range of output)	
with voltage outputs, min.	1 kΩ
 with voltage outputs, capacitive load, max. 	100 nF
with current outputs, max.	500 Ω
with current outputs, inductive load, max.	1 mH
Cable length	
• shielded, max.	200 m
Analog value generation for the inputs	
Integration and conversion time/resolution per channel	
 Resolution with overrange (bit including sign), max. 	16 bit
Integration time, parameterizable	Yes; 2.5 / 16.67 / 20 / 100 ms, acts on all channels
Interference voltage suppression for interference frequency f1 in Hz	400 / 60 / 50 / 10
frequency f1 in Hz Smoothing of measured values	
parameterizable	Yes
Step: None	Yes
• Step: None	Yes
• Step: Nedium	Yes
Step: High	Yes
Analog value generation for the outputs	
Integration and conversion time/resolution per channel	
mogration and conversion time/resolution per chamile	

- Decelution with everrange (bit including sign), may	16 hit
Resolution with overrange (bit including sign), max. Settling time.	16 bit
Settling time	1.5 mg
for resistive loadfor capacitive load	1.5 ms 2.5 ms
for inductive load	2.5 ms
Encoder	2.3 1118
Connection of signal encoders • for voltage measurement	Yes
for current measurement as 4-wire transducer	Yes
for resistance measurement with two-wire	Yes
connection	166
• for resistance measurement with three-wire	Yes
connectionfor resistance measurement with four-wire	Yes
connection	
Connectable encoders	
• 2-wire sensor	Yes
permissible quiescent current (2-wire sensor), max.	1.5 mA
Encoder signals, incremental encoder (asymmetrical)	
Input voltage	24 V
 Input frequency, max. 	100 kHz
 Counting frequency, max. 	400 kHz; with quadruple evaluation
Signal filter, parameterizable	Yes
 Incremental encoder with A/B tracks, 90° phase offset 	Yes
 Incremental encoder with A/B tracks, 90° phase offset and zero track 	Yes
• pulse encoder	Yes
 pulse encoder with direction 	Yes
 pulse encoder with one impulse signal per count direction 	Yes
Errors/accuracies	
Linearity error (relative to input range), (+/-)	0.1 %
Temperature error (relative to input range), (+/-)	0.005 %/K
Crosstalk between the inputs, max.	-60 dB
Repeat accuracy in steady state at 25 °C (relative to input range), (+/-)	0.05 %
Output ripple (relative to output range, bandwidth 0 to 50 kHz), (+/-)	0.02 %
Linearity error (relative to output range), (+/-)	0.15 %
Linearity error (relative to output range), (+/-) Temperature error (relative to output range), (+/-)	0.15 % 0.005 %/K
Temperature error (relative to output range), (+/-)	0.005 %/K
Temperature error (relative to output range), (+/-) Crosstalk between the outputs, max. Repeat accuracy in steady state at 25 °C (relative to	0.005 %/K -80 dB
Temperature error (relative to output range), (+/-) Crosstalk between the outputs, max. Repeat accuracy in steady state at 25 °C (relative to output range), (+/-)	0.005 %/K -80 dB
Temperature error (relative to output range), (+/-) Crosstalk between the outputs, max. Repeat accuracy in steady state at 25 °C (relative to output range), (+/-) Operational error limit in overall temperature range	0.005 %/K -80 dB 0.05 %
Temperature error (relative to output range), (+/-) Crosstalk between the outputs, max. Repeat accuracy in steady state at 25 °C (relative to output range), (+/-) Operational error limit in overall temperature range • Voltage, relative to input range, (+/-)	0.005 %/K -80 dB 0.05 %
Temperature error (relative to output range), (+/-) Crosstalk between the outputs, max. Repeat accuracy in steady state at 25 °C (relative to output range), (+/-) Operational error limit in overall temperature range • Voltage, relative to input range, (+/-) • Current, relative to input range, (+/-)	0.005 %/K -80 dB 0.05 % 0.3 % 0.3 %
Temperature error (relative to output range), (+/-) Crosstalk between the outputs, max. Repeat accuracy in steady state at 25 °C (relative to output range), (+/-) Operational error limit in overall temperature range • Voltage, relative to input range, (+/-) • Current, relative to input range, (+/-) • Resistance, relative to input range, (+/-)	0.005 %/K -80 dB 0.05 % 0.3 % 0.3 % 0.3 % Pt100 Standard: ±2 K, Pt100 Climate: ±1 K, Ni100 Standard: ±1.2 K,
Temperature error (relative to output range), (+/-) Crosstalk between the outputs, max. Repeat accuracy in steady state at 25 °C (relative to output range), (+/-) Operational error limit in overall temperature range • Voltage, relative to input range, (+/-) • Current, relative to input range, (+/-) • Resistance, relative to input range, (+/-) • Resistance thermometer, relative to input range, (+/-)	0.005 %/K -80 dB 0.05 % 0.3 % 0.3 % 0.3 % Pt100 Standard: ±2 K, Pt100 Climate: ±1 K, Ni100 Standard: ±1.2 K, Ni100 Climate: ±1 K
Temperature error (relative to output range), (+/-) Crosstalk between the outputs, max. Repeat accuracy in steady state at 25 °C (relative to output range), (+/-) Operational error limit in overall temperature range • Voltage, relative to input range, (+/-) • Current, relative to input range, (+/-) • Resistance, relative to input range, (+/-) • Resistance thermometer, relative to input range, (+/-) • Voltage, relative to output range, (+/-)	0.005 %/K -80 dB 0.05 % 0.3 % 0.3 % 0.3 % Pt100 Standard: ±2 K, Pt100 Climate: ±1 K, Ni100 Standard: ±1.2 K, Ni100 Climate: ±1 K
Temperature error (relative to output range), (+/-) Crosstalk between the outputs, max. Repeat accuracy in steady state at 25 °C (relative to output range), (+/-) Operational error limit in overall temperature range • Voltage, relative to input range, (+/-) • Current, relative to input range, (+/-) • Resistance, relative to input range, (+/-) • Resistance thermometer, relative to input range, (+/-) • Voltage, relative to output range, (+/-) • Current, relative to output range, (+/-)	0.005 %/K -80 dB 0.05 % 0.3 % 0.3 % 0.3 % Pt100 Standard: ±2 K, Pt100 Climate: ±1 K, Ni100 Standard: ±1.2 K, Ni100 Climate: ±1 K
Temperature error (relative to output range), (+/-) Crosstalk between the outputs, max. Repeat accuracy in steady state at 25 °C (relative to output range), (+/-) Operational error limit in overall temperature range • Voltage, relative to input range, (+/-) • Current, relative to input range, (+/-) • Resistance, relative to input range, (+/-) • Resistance thermometer, relative to input range, (+/-) • Voltage, relative to output range, (+/-) • Current, relative to output range, (+/-) Basic error limit (operational limit at 25 °C) • Voltage, relative to input range, (+/-) • Current, relative to input range, (+/-)	0.005 %/K -80 dB 0.05 % 0.3 % 0.3 % 0.3 % Pt100 Standard: ±2 K, Pt100 Climate: ±1 K, Ni100 Standard: ±1.2 K, Ni100 Climate: ±1 K 0.3 % 0.3 %
Temperature error (relative to output range), (+/-) Crosstalk between the outputs, max. Repeat accuracy in steady state at 25 °C (relative to output range), (+/-) Operational error limit in overall temperature range • Voltage, relative to input range, (+/-) • Current, relative to input range, (+/-) • Resistance, relative to input range, (+/-) • Resistance thermometer, relative to input range, (+/-) • Voltage, relative to output range, (+/-) • Current, relative to output range, (+/-) Basic error limit (operational limit at 25 °C) • Voltage, relative to input range, (+/-)	0.005 %/K -80 dB 0.05 % 0.3 % 0.3 % 0.3 % Pt100 Standard: ±2 K, Pt100 Climate: ±1 K, Ni100 Standard: ±1.2 K, Ni100 Climate: ±1 K 0.3 % 0.3 % 0.3 %
Temperature error (relative to output range), (+/-) Crosstalk between the outputs, max. Repeat accuracy in steady state at 25 °C (relative to output range), (+/-) Operational error limit in overall temperature range • Voltage, relative to input range, (+/-) • Current, relative to input range, (+/-) • Resistance, relative to input range, (+/-) • Resistance thermometer, relative to input range, (+/-) • Voltage, relative to output range, (+/-) • Current, relative to output range, (+/-) Basic error limit (operational limit at 25 °C) • Voltage, relative to input range, (+/-) • Current, relative to input range, (+/-)	0.005 %/K -80 dB 0.05 % 0.3 % 0.3 % 0.3 % Pt100 Standard: ±2 K, Pt100 Climate: ±1 K, Ni100 Standard: ±1.2 K, Ni100 Climate: ±1 K 0.3 % 0.3 % 0.3 % 0.2 % 0.2 % 0.2 % Pt100 Standard: ±1 K, Pt100 Climate: ±0.5 K, Ni100 Standard: ±0.6 K,
Temperature error (relative to output range), (+/-) Crosstalk between the outputs, max. Repeat accuracy in steady state at 25 °C (relative to output range), (+/-) Operational error limit in overall temperature range • Voltage, relative to input range, (+/-) • Current, relative to input range, (+/-) • Resistance, relative to input range, (+/-) • Resistance thermometer, relative to input range, (+/-) • Voltage, relative to output range, (+/-) • Current, relative to output range, (+/-) Basic error limit (operational limit at 25 °C) • Voltage, relative to input range, (+/-) • Current, relative to input range, (+/-) • Resistance, relative to input range, (+/-) • Resistance thermometer, relative to input range, (+/-)	0.005 %/K -80 dB 0.05 % 0.3 % 0.3 % 0.3 % Pt100 Standard: ±2 K, Pt100 Climate: ±1 K, Ni100 Standard: ±1.2 K, Ni100 Climate: ±1 K 0.3 % 0.3 % 0.2 % 0.2 % 0.2 % Pt100 Standard: ±1 K, Pt100 Climate: ±0.5 K, Ni100 Standard: ±0.6 K, Ni100 Climate: ±0.5 K
Temperature error (relative to output range), (+/-) Crosstalk between the outputs, max. Repeat accuracy in steady state at 25 °C (relative to output range), (+/-) Operational error limit in overall temperature range • Voltage, relative to input range, (+/-) • Resistance, relative to input range, (+/-) • Resistance thermometer, relative to input range, (+/-) • Voltage, relative to output range, (+/-) • Current, relative to output range, (+/-) • Current, relative to output range, (+/-) • Current, relative to input range, (+/-) • Resistance, relative to input range, (+/-) • Resistance, relative to input range, (+/-) • Resistance thermometer, relative to input range, (+/-) • Resistance thermometer, relative to input range, (+/-) • Resistance thermometer, relative to input range, (+/-)	0.005 %/K -80 dB 0.05 % 0.3 % 0.3 % Pt100 Standard: ±2 K, Pt100 Climate: ±1 K, Ni100 Standard: ±1.2 K, Ni100 Climate: ±1 K 0.3 % 0.3 % 0.2 % 0.2 % Pt100 Standard: ±1 K, Pt100 Climate: ±0.5 K, Ni100 Standard: ±0.6 K, Ni100 Climate: ±0.5 K
Temperature error (relative to output range), (+/-) Crosstalk between the outputs, max. Repeat accuracy in steady state at 25 °C (relative to output range), (+/-) Operational error limit in overall temperature range • Voltage, relative to input range, (+/-) • Resistance, relative to input range, (+/-) • Resistance thermometer, relative to input range, (+/-) • Voltage, relative to output range, (+/-) • Current, relative to output range, (+/-) • Current, relative to output range, (+/-) • Current, relative to input range, (+/-) • Current, relative to input range, (+/-) • Resistance, relative to input range, (+/-) • Resistance thermometer, relative to input range, (+/-) • Resistance thermometer, relative to input range, (+/-) • Current, relative to output range, (+/-) • Current, relative to output range, (+/-)	0.005 %/K -80 dB 0.05 % 0.3 % 0.3 % 0.3 % Pt100 Standard: ±2 K, Pt100 Climate: ±1 K, Ni100 Standard: ±1.2 K, Ni100 Climate: ±1 K 0.3 % 0.3 % 0.2 % 0.2 % Pt100 Standard: ±1 K, Pt100 Climate: ±0.5 K, Ni100 Standard: ±0.6 K, Ni100 Climate: ±0.5 K 0.2 % 0.2 % 0.2 % 0.2 %
Temperature error (relative to output range), (+/-) Crosstalk between the outputs, max. Repeat accuracy in steady state at 25 °C (relative to output range), (+/-) Operational error limit in overall temperature range • Voltage, relative to input range, (+/-) • Resistance, relative to input range, (+/-) • Resistance thermometer, relative to input range, (+/-) • Voltage, relative to output range, (+/-) • Current, relative to output range, (+/-) • Current, relative to output range, (+/-) • Current, relative to input range, (+/-) • Current, relative to input range, (+/-) • Resistance, relative to input range, (+/-) • Resistance, relative to input range, (+/-) • Resistance thermometer, relative to input range, (+/-) • Resistance thermometer, relative to input range, (+/-)	0.005 %/K -80 dB 0.05 % 0.3 % 0.3 % 0.3 % Pt100 Standard: ±2 K, Pt100 Climate: ±1 K, Ni100 Standard: ±1.2 K, Ni100 Climate: ±1 K 0.3 % 0.3 % 0.2 % 0.2 % Pt100 Standard: ±1 K, Pt100 Climate: ±0.5 K, Ni100 Standard: ±0.6 K, Ni100 Climate: ±0.5 K 0.2 % 0.2 % 0.2 % 0.2 %

interference < rated value of input range), min.	
 Common mode voltage, max. 	10 V
Common mode interference, min.	60 dB; at 400 Hz: 50 dB
Interfaces	
Number of PROFINET interfaces	1
1. Interface	
Interface types	
RJ 45 (Ethernet)	Yes; X1
 Number of ports 	2
integrated switch	Yes
Protocols	
IP protocol	Yes; IPv4
 PROFINET IO Controller 	Yes
 PROFINET IO Device 	Yes
 SIMATIC communication 	Yes
Open IE communication	Yes; Optionally also encrypted
Web server	Yes
Media redundancy	Yes
PROFINET IO Controller	
Services	
— PG/OP communication	Yes
— Isochronous mode	Yes
Direct data exchange	Yes; Requirement: IRT and isochronous mode (MRPD optional)
— IRT	Yes
— PROFlenergy	Yes; per user program
— Prioritized startup	Yes; Max. 32 PROFINET devices
 Number of connectable IO Devices, max. 	128; In total, up to 256 distributed I/O devices can be connected via AS-i, PROFIBUS or PROFINET
 Of which IO devices with IRT, max. 	64
Number of connectable IO Devices for RT,	128
max.	120
— of which in line, max.	128
 Number of IO Devices that can be 	8; in total across all interfaces
simultaneously activated/deactivated, max.	
 Number of IO Devices per tool, max. 	8
Updating times	The minimum value of the update time also depends on communication
	share set for PROFINET IO, on the number of IO devices, and on the quantity of configured user data
Update time for IRT	
— for send cycle of 250 μs	250 µs to 4 ms; Note: In the case of IRT with isochronous mode, the
	minimum update time of 625 µs of the isochronous OB is decisive
— for send cycle of 500 μs	500 µs to 8 ms; Note: In the case of IRT with isochronous mode, the
	minimum update time of 625 μs of the isochronous OB is decisive
— for send cycle of 1 ms	1 ms to 16 ms
— for send cycle of 2 ms	2 ms to 32 ms
— for send cycle of 4 ms	4 ms to 64 ms
 With IRT and parameterization of "odd" send cycles 	Update time = set "odd" send clock (any multiple of 125 μs: 375 μs, 625 μs 3 875 μs)
Update time for RT	μο σ σ, σ μο)
— for send cycle of 250 μs	250 µs to 128 ms
— for send cycle of 500 μs	500 µs to 256 ms
— for send cycle of 1 ms	1 ms to 512 ms
— for send cycle of 2 ms	2 ms to 512 ms
— for send cycle of 4 ms	4 ms to 512 ms
PROFINET IO Device	
Services	
— PG/OP communication	Yes
Isochronous mode	No
— IRT	Yes
— PROFlenergy	Yes; per user program
— Shared device	Yes
Number of IO Controllers with shared device,	4

max.	
 activation/deactivation of I-devices 	Yes; per user program
Asset management record	Yes; per user program
Interface types	
RJ 45 (Ethernet)	
• 100 Mbps	Yes
 Autonegotiation 	Yes
 Autocrossing 	Yes
Industrial Ethernet status LED	Yes
Protocols	
Number of connections	
Number of connections, max.	96; via integrated interfaces of the CPU and connected CPs / CMs
Number of connections reserved for ES/HMI/web	10
Number of connections via integrated interfaces	64
Number of S7 routing paths	16
Redundancy mode	Ves
H-Sync forwarding Media redundancy	Yes
Media redundancy	only via 1st interface (V1)
— Media redundancy — MRP	only via 1st interface (X1)
— IVINF	Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP Manager; MRP Client
 MRP interconnection, supported 	Yes; as MRP ring node according to IEC 62439-2 Edition 3.0
— MRPD	Yes; Requirement: IRT
 Switchover time on line break, typ. 	200 ms; For MRP, bumpless for MRPD
— Number of stations in the ring, max.	50
SIMATIC communication	
PG/OP communication	Yes; encryption with TLS V1.3 pre-selected
 S7 routing 	Yes
 S7 communication, as server 	Yes
 S7 communication, as client 	Yes
User data per job, max.	See online help (S7 communication, user data size)
Open IE communication	
• TCP/IP	Yes
— Data length, max.	64 kbyte
 — several passive connections per port, supported 	Yes
• ISO-on-TCP (RFC1006)	Yes
— Data length, max.	64 kbyte
• UDP	Yes
— Data length, max.	2 kbyte; 1 472 bytes for UDP broadcast
— UDP multicast	Yes; Max. 5 multicast circuits
• DHCP	Yes
• DNS	Yes
• SNMP	Yes
• DCP	Yes
• LLDP	Yes
Encryption	Yes; Optional
Web server	
• HTTP	Yes; Standard and user pages
• HTTPS	Yes; Standard and user pages
OPC UA	
 Runtime license required 	Yes; "Small" license required
OPC UA Client	Yes
 Application authentication 	Yes
— Security policies	Available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256
User authentication	"anonymous" or by user name & password
 Number of connections, max. 	4
 Number of nodes of the client interfaces, max. 	1 000
— Number of elements for one call of	300
OPC_UA_NodeGetHandleList/OPC_UA_ReadList/	

max.	
Number of elements for one call of	20
OPC_UA_NameSpaceGetIndexList, max.	20
 Number of elements for one call of OPC_UA_MethodGetHandleList, max. 	100
Number of simultaneous calls of the client	1
instructions per connection (except OPC_UA_ReadList,OPC_UA_WriteList,OPC_UA_M max.	
 Number of simultaneous calls of the client instructions 	5
OPC_UA_ReadList,OPC_UA_WriteList and OPC_UA_MethodCall, max.	
Number of registerable nodes, max.	5 000
 Number of registerable method calls of OPC_UA_MethodCall, max. 	100
 Number of inputs/outputs when calling OPC_UA_MethodCall, max. 	20
OPC UA Server	Yes; Data access (read, write, subscribe), method call, custom address space
 Application authentication 	Yes
— Security policies	Available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256
 User authentication 	"anonymous" or by user name & password
 — GDS support (certificate management) 	Yes
— Number of sessions, max.	32
 Number of accessible variables, max. 	50 000
 Number of registerable nodes, max. 	10 000
 Number of subscriptions per session, max. 	20
— Sampling interval, min.	100 ms
— Publishing interval, min.	500 ms
 Number of server methods, max. 	20
 Number of inputs/outputs per server method, max. 	20
 Number of monitored items, max. 	1 000; for 1 s sampling interval and 1 s send interval
 Number of server interfaces, max. 	10 of each "Server interfaces" / "Companion specification" type and 20 of the type "Reference namespace"
 Number of nodes for user-defined server interfaces, max. 	1 000
 Alarms and Conditions 	Yes
 Number of program alarms 	100
Number of alarms for system diagnostics	50
Further protocols	
MODBUS	Yes; MODBUS TCP
Isochronous mode	
Equidistance	Yes
S7 message functions	
Number of login stations for message functions, max.	32
Program alarms	Yes
Number of configurable program messages, max.	5 000; Program messages are generated by the "Program_Alarm" block, ProDiag or GRAPH
Number of loadable program messages in RUN, max.	2 500
Number of simultaneously active program alarms	
 Number of program alarms 	600
 Number of alarms for system diagnostics 	100
Number of alarms for motion technology objects	80
Test commissioning functions	
Joint commission (Team Engineering)	Yes; Parallel online access possible for up to 5 engineering systems
Status block	Yes; Up to 8 simultaneously (in total across all ES clients)
Single step	No
Number of breakpoints	8
Status/control	
 Status/control variable 	Yes

 Variables 	Inputs/outputs, memory bits, DBs, distributed I/Os, timers, counters
 Number of variables, max. 	
— of which status variables, max.	200; per job
— of which control variables, max.	200; per job
Forcing	
• Forcing	Yes
Forcing, variables	Peripheral inputs/outputs
Number of variables, max.	200
Diagnostic buffer	
• present	Yes
 Number of entries, max. 	1 000
— of which powerfail-proof	500
Traces	
Number of configurable Traces	4; Up to 512 KB of data per trace are possible
Interrupts/diagnostics/status information	
Alarms	
Diagnostic alarm	Yes
Hardware interrupt	Yes
Diagnoses	
 Monitoring the supply voltage 	Yes
Wire-break	Yes; for analog inputs/outputs, see description in manual
 Short-circuit 	Yes; for analog outputs, see description in manual
A/B transition error at incremental encoder	Yes
Diagnostics indication LED	
RUN/STOP LED	Yes
• ERROR LED	Yes
MAINT LED	Yes
STOP ACTIVE LED	Yes
 Monitoring of the supply voltage (PWR-LED) 	Yes
 Channel status display 	Yes
 for channel diagnostics 	Yes; For analog inputs/outputs
for channel diagnosticsConnection display LINK TX/RX	Yes; For analog inputs/outputs Yes
_	
Connection display LINK TX/RX	Yes Yes; Note: The number of technology objects affects the cycle time of
Connection display LINK TX/RX Supported technology objects Motion Control	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool
Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for	Yes Yes; Note: The number of technology objects affects the cycle time of
Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool
Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800
Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800
Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 80
Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 80 160
Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80
Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20
Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160
Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20
Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160
Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40
Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value)	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40
Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40
Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per positioning axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40 5 10 Yes; Universal PID controller with integrated optimization
Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Step	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40 5 10 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves
Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_AStep PID-Temp	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40 5 10 Yes; Universal PID controller with integrated optimization
Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Astep PID-Temp Counting and measuring	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature
Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Step PID-Temp Counting and measuring High-speed counter	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40 5 10 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves
Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Astep PID-Temp Counting and measuring	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature
Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Temp Counting and measuring High-speed counter Integrated Functions Counter	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40 5 10 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature Yes
Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Temp Counting and measuring High-speed counter Integrated Functions Counter Number of counters	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40 5 10 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature Yes 6; Of which max. 4x A/B/N
Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Temp Counting and measuring High-speed counter Integrated Functions Counter	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40 5 10 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature Yes

Continuous counting	Yes
Continuous countingCounter response parameterizable	Yes
Hardware gate via digital input	Yes
Software gate	Yes
Event-controlled stop	Yes
Synchronization via digital input	Yes
Counting range, parameterizable	Yes
Comparator	163
Number of comparators	2; per count channel; see manual for details
Direction dependency	Yes
— Can be changed from user program	Yes
Position detection	
Incremental acquisition	Yes
 Suitable for S7-1500 Motion Control 	Yes
Measuring functions	
Measuring time, parameterizable	Yes
Dynamic measurement period adjustment	Yes
Number of thresholds, parameterizable	2
Measuring range	
— Frequency measurement, min.	0.04 Hz
— Frequency measurement, max.	400 kHz; with quadruple evaluation
Cycle duration measurement, min.	2.5 μs
Cycle duration measurement, max.	25 s
Accuracy	
 Frequency measurement 	100 ppm; depending on measuring interval and signal evaluation
 Cycle duration measurement 	100 ppm; depending on measuring interval and signal evaluation
 Velocity measurement 	100 ppm; depending on measuring interval and signal evaluation
Potential separation	
Potential separation digital inputs	
between the channels	No
 between the channels, in groups of 	16
Potential separation digital outputs	
 between the channels 	No
between the channels, in groups of	16
Potential separation channels	
 between the channels and backplane bus 	Yes
Between the channels and load voltage L+	No
Isolation	
Isolation tested with	707 V DC (type test)
Ambient conditions	
Ambient temperature during operation	
 horizontal installation, min. 	-25 °C; No condensation
 horizontal installation, max. 	60 °C; note derating data for onboard I/O in the manual. Display: 50 °C, at an operating temperature of typically 50 °C, the display is switched off
 vertical installation, min. 	-25 °C; No condensation
vertical installation, max.	40 °C; note derating data for onboard I/O in the manual. Display: 40 °C, at an operating temperature of typically 40 °C, the display is switched off
Ambient temperature during storage/transportation	
• min.	-40 °C
• max.	70 °C
Altitude during operation relating to sea level	F 000 mg Destrictions for in 1 H C HC 1 H C 2000
Installation altitude above sea level, max.	5 000 m; Restrictions for installation altitudes > 2 000 m, see manual
configuration / header	
configuration / programming / header	
Programming language	V
Programming language — LAD	Yes
Programming language — LAD — FBD	Yes
Programming language — LAD — FBD — STL	Yes Yes
Programming language — LAD — FBD	Yes

Know-how protection	
 User program protection/password protection 	Yes
 Copy protection 	Yes
Block protection	Yes
Access protection	
 protection of confidential configuration data 	Yes
 Password for display 	Yes
 Protection level: Write protection 	Yes
 Protection level: Read/write protection 	Yes
 Protection level: Complete protection 	Yes
programming / cycle time monitoring / header	
 lower limit 	adjustable minimum cycle time
upper limit	adjustable maximum cycle time
Dimensions	
Width	85 mm
Height	147 mm
Depth	129 mm
Weights	
Weight, approx.	1 050 g

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