6ES7512-1CK01-0AB0

Data sheet



SIMATIC S7-1500 Compact CPU CPU 1512C-1 PN, central processing unit with working memory 250 KB for program and 1 MB for data, 32 digital inputs, 32 digital outputs, 5 analog inputs, 2 analog outputs, 6 high speed counters, 4 high speed outputs for PTO/PWM/frequency output 1. interface: PROFINET IRT with 2 port switch, 48 NS bit-performance, incl. front connector push-in, SIMATIC memory card necessary

General information	
Product type designation	CPU 1512C-1 PN
HW functional status	FS03
Firmware version	V2.9
Product function	
I&M data	Yes; I&M0 to I&M3
Isochronous mode	Yes; With minimum OB 6x cycle of 625 µs (distributed)
Engineering with	
 STEP 7 TIA Portal configurable/integrated from version 	V17 (FW V2.9) / V15 (FW V2.5) or higher; with older TIA Portal versions configurable as 6ES7512-1CK00-0AB0
Configuration control	
via dataset	Yes
Display	
Screen diagonal [cm]	3.45 cm
Control elements	
Number of keys	8
Mode buttons	2
Supply voltage	
Type of supply voltage	DC
Rated value (DC)	24 V
permissible range, lower limit (DC)	19.2 V; 20.4 V DC, for supplying the digital inputs/outputs
permissible range, upper limit (DC)	28.8 V
Reverse polarity protection	Yes
Mains buffering	
 Mains/voltage failure stored energy time 	5 ms; Refers to the power supply on the CPU section
Repeat rate, min.	1/s
Input current	
Current consumption (rated value)	0.8 A; Without load; 18.8 A: CPU + load
Current consumption, max.	1 A; Without load; 19 A: CPU + load
Inrush current, max.	1.9 A; Rated value
l²t	0.34 A ² ·s
Digital inputs	
from load voltage L+ (without load), max.	20 mA; per group
Digital outputs	
◆ from load voltage L+, max.	30 mA; Per group, without load
output voltage / header	
Rated value (DC)	24 V
Encoder supply	
Number of outputs	2; One common 24 V encoder supply per 16 digital inputs

24 V encoder supply	
• 24 V	Yes; L+ (-0.8 V)
Short-circuit protection	Yes
Output current, max.	1 A
Power	
Infeed power to the backplane bus	10 W
Power consumption from the backplane bus (balanced)	9 W
Power loss	45.014
Power loss, typ.	15.2 W
Memory	
Number of slots for SIMATIC memory card	1
SIMATIC memory card required	Yes
Work memory	
integrated (for program)	250 kbyte
integrated (for data)	1 Mbyte
Load memory	
 Plug-in (SIMATIC Memory Card), max. 	32 Gbyte
Backup	
maintenance-free	Yes
CPU processing times	
for bit operations, typ.	48 ns
for word operations, typ.	58 ns
for fixed point arithmetic, typ.	77 ns
for floating point arithmetic, typ.	307 ns
CPU-blocks	001 III
	4.000: Pleaks (OR FR FC PR) and LIDTs
Number of elements (total)	4 000; Blocks (OB, FB, FC, DB) and UDTs
DB	
Number range	1 60 999; subdivided into: number range that can be used by the user: 1 59 999, and number range of DBs created via SFC 86: 60 000
	60 999
• Size, max.	1 Mbyte; For DBs with absolute addressing, the max. size is 64 KB
	, , , , , , , , , , , , , , , , , , , ,
FB	
	0 65 535
Number range	
Number rangeSize, max.	0 65 535 250 kbyte
Number rangeSize, max.	250 kbyte
Number rangeSize, max.FCNumber range	250 kbyte 0 65 535
 Number range Size, max. FC Number range Size, max. 	250 kbyte
 Number range Size, max. FC Number range Size, max. OB	250 kbyte 0 65 535 250 kbyte
 Number range Size, max. FC Number range Size, max. OB Size, max. 	250 kbyte 0 65 535 250 kbyte 250 kbyte
 Number range Size, max. FC Number range Size, max. OB Size, max. Number of free cycle OBs 	250 kbyte 0 65 535 250 kbyte 250 kbyte 100
 Number range Size, max. FC Number range Size, max. OB Size, max. Number of free cycle OBs Number of time alarm OBs 	250 kbyte 0 65 535 250 kbyte 250 kbyte 100 20
 Number range Size, max. FC Number range Size, max. OB Size, max. Number of free cycle OBs Number of time alarm OBs Number of delay alarm OBs 	250 kbyte 0 65 535 250 kbyte 250 kbyte 100 20 20
 Number range Size, max. FC Number range Size, max. OB Size, max. Number of free cycle OBs Number of time alarm OBs Number of delay alarm OBs Number of cyclic interrupt OBs 	250 kbyte 0 65 535 250 kbyte 250 kbyte 100 20 20 20; With minimum OB 3x cycle of 500 µs
 Number range Size, max. FC Number range Size, max. OB Size, max. Number of free cycle OBs Number of time alarm OBs Number of delay alarm OBs Number of cyclic interrupt OBs Number of process alarm OBs 	250 kbyte 0 65 535 250 kbyte 250 kbyte 100 20 20 20; With minimum OB 3x cycle of 500 μs 50
 Number range Size, max. Number range Size, max. OB Size, max. Number of free cycle OBs Number of time alarm OBs Number of delay alarm OBs Number of cyclic interrupt OBs Number of process alarm OBs Number of DPV1 alarm OBs 	250 kbyte 0 65 535 250 kbyte 250 kbyte 100 20 20 20; With minimum OB 3x cycle of 500 μs 50 3
 Number range Size, max. FC Number range Size, max. OB Size, max. Number of free cycle OBs Number of time alarm OBs Number of delay alarm OBs Number of cyclic interrupt OBs Number of process alarm OBs Number of DPV1 alarm OBs Number of isochronous mode OBs 	250 kbyte 0 65 535 250 kbyte 250 kbyte 100 20 20 20; With minimum OB 3x cycle of 500 μs 50 3 1
 Number range Size, max. FC Number range Size, max. OB Size, max. Number of free cycle OBs Number of time alarm OBs Number of delay alarm OBs Number of cyclic interrupt OBs Number of process alarm OBs Number of DPV1 alarm OBs Number of isochronous mode OBs Number of technology synchronous alarm OBs 	250 kbyte 0 65 535 250 kbyte 250 kbyte 100 20 20 20; With minimum OB 3x cycle of 500 μs 50 3 1
 Number range Size, max. FC Number range Size, max. OB Size, max. Number of free cycle OBs Number of time alarm OBs Number of delay alarm OBs Number of cyclic interrupt OBs Number of process alarm OBs Number of DPV1 alarm OBs Number of isochronous mode OBs Number of technology synchronous alarm OBs Number of startup OBs 	250 kbyte 0 65 535 250 kbyte 250 kbyte 100 20 20 20; With minimum OB 3x cycle of 500 μs 50 3 1 2 100
 Number range Size, max. Number range Size, max. OB Size, max. Number of free cycle OBs Number of time alarm OBs Number of delay alarm OBs Number of cyclic interrupt OBs Number of process alarm OBs Number of DPV1 alarm OBs Number of isochronous mode OBs Number of technology synchronous alarm OBs Number of startup OBs Number of asynchronous error OBs 	250 kbyte 0 65 535 250 kbyte 250 kbyte 100 20 20 20; With minimum OB 3x cycle of 500 μs 50 3 1 2 100 4
 Number range Size, max. Number range Size, max. Size, max. Number of free cycle OBs Number of time alarm OBs Number of delay alarm OBs Number of cyclic interrupt OBs Number of process alarm OBs Number of DPV1 alarm OBs Number of isochronous mode OBs Number of startup OBs Number of startup OBs Number of startup OBs Number of synchronous error OBs Number of synchronous error OBs 	250 kbyte 0 65 535 250 kbyte 250 kbyte 100 20 20; With minimum OB 3x cycle of 500 μs 50 3 1 2 100 4 2
 Number range Size, max. FC Number range Size, max. Number of free cycle OBs Number of time alarm OBs Number of delay alarm OBs Number of cyclic interrupt OBs Number of process alarm OBs Number of DPV1 alarm OBs Number of isochronous mode OBs Number of startup OBs Number of asynchronous error OBs Number of diagnostic alarm OBs 	250 kbyte 0 65 535 250 kbyte 250 kbyte 100 20 20 20; With minimum OB 3x cycle of 500 μs 50 3 1 2 100 4
 Number range Size, max. Number range Size, max. Size, max. Number of free cycle OBs Number of time alarm OBs Number of delay alarm OBs Number of cyclic interrupt OBs Number of process alarm OBs Number of DPV1 alarm OBs Number of isochronous mode OBs Number of startup OBs Number of startup OBs Number of startup OBs Number of synchronous error OBs Number of synchronous error OBs 	250 kbyte 0 65 535 250 kbyte 250 kbyte 100 20 20; With minimum OB 3x cycle of 500 μs 50 3 1 2 100 4 2
 Number range Size, max. FC Number range Size, max. Number of free cycle OBs Number of time alarm OBs Number of delay alarm OBs Number of cyclic interrupt OBs Number of process alarm OBs Number of DPV1 alarm OBs Number of isochronous mode OBs Number of startup OBs Number of asynchronous error OBs Number of diagnostic alarm OBs 	250 kbyte 0 65 535 250 kbyte 250 kbyte 100 20 20; With minimum OB 3x cycle of 500 μs 50 3 1 2 100 4 2
 Number range Size, max. Number range Size, max. Number of free cycle OBs Number of time alarm OBs Number of delay alarm OBs Number of process alarm OBs Number of DPV1 alarm OBs Number of isochronous mode OBs Number of startup OBs Number of diagnostic alarm OBs Number of diagnostic alarm OBs 	250 kbyte 0 65 535 250 kbyte 250 kbyte 100 20 20 20; With minimum OB 3x cycle of 500 μs 50 3 1 2 100 4 2 1
 Number range Size, max. PC Number range Size, max. OB Size, max. Number of free cycle OBs Number of time alarm OBs Number of delay alarm OBs Number of cyclic interrupt OBs Number of process alarm OBs Number of DPV1 alarm OBs Number of isochronous mode OBs Number of startup OBs Number of startup OBs Number of startup OBs Number of asynchronous error OBs Number of diagnostic alarm OBs Nesting depth per priority class 	250 kbyte 0 65 535 250 kbyte 250 kbyte 100 20 20 20; With minimum OB 3x cycle of 500 μs 50 3 1 2 100 4 2 1
 Number range Size, max. Number range Size, max. OB Size, max. Number of free cycle OBs Number of time alarm OBs Number of delay alarm OBs Number of cyclic interrupt OBs Number of process alarm OBs Number of DPV1 alarm OBs Number of isochronous mode OBs Number of startup OBs Number of startup OBs Number of synchronous error OBs Number of asynchronous error OBs Number of diagnostic alarm OBs Nesting depth per priority class Counters, timers and their retentivity	250 kbyte 250 kbyte 250 kbyte 250 kbyte 200 20 20; With minimum OB 3x cycle of 500 µs 50 3 1 2 100 4 2 1
 Number range Size, max. Number range Size, max. Number of free cycle OBs Number of time alarm OBs Number of delay alarm OBs Number of cyclic interrupt OBs Number of process alarm OBs Number of DPV1 alarm OBs Number of isochronous mode OBs Number of startup OBs Number of startup OBs Number of startup OBs Number of diagnostic alarm OBs Number of synchronous error OBs Number of diagnostic alarm OBs Nesting depth per priority class Counters, timers and their retentivity S7 counter Number 	250 kbyte 0 65 535 250 kbyte 250 kbyte 100 20 20 20; With minimum OB 3x cycle of 500 μs 50 3 1 2 100 4 2 1
 Number range Size, max. Number range Size, max. Number of free cycle OBs Number of time alarm OBs Number of delay alarm OBs Number of process alarm OBs Number of DPV1 alarm OBs Number of isochronous mode OBs Number of startup OBs Number of startup OBs Number of startup OBs Number of diagnostic alarm OBs Number of synchronous error OBs Number of diagnostic alarm OBs Nesting depth per priority class Counters, timers and their retentivity S7 counter Number Retentivity 	250 kbyte 0 65 535 250 kbyte 250 kbyte 100 20 20; With minimum OB 3x cycle of 500 μs 50 3 1 2 100 4 2 1
 Number range Size, max. Number range Size, max. OB Size, max. Number of free cycle OBs Number of time alarm OBs Number of delay alarm OBs Number of cyclic interrupt OBs Number of process alarm OBs Number of DPV1 alarm OBs Number of isochronous mode OBs Number of startup OBs Number of startup OBs Number of asynchronous error OBs Number of diagnostic alarm OBs Number of diagnostic alarm OBs Nesting depth per priority class Counters, timers and their retentivity S7 counter Number Retentivity — adjustable 	250 kbyte 250 kbyte 250 kbyte 250 kbyte 200 20 20; With minimum OB 3x cycle of 500 µs 50 3 1 2 100 4 2 1
 Number range Size, max. Number range Size, max. Number of free cycle OBs Number of time alarm OBs Number of delay alarm OBs Number of process alarm OBs Number of DPV1 alarm OBs Number of isochronous mode OBs Number of startup OBs Number of startup OBs Number of startup OBs Number of diagnostic alarm OBs Number of synchronous error OBs Number of diagnostic alarm OBs Nesting depth per priority class Counters, timers and their retentivity S7 counter Number Retentivity 	250 kbyte 0 65 535 250 kbyte 250 kbyte 100 20 20; With minimum OB 3x cycle of 500 μs 50 3 1 2 100 4 2 1

Retentivity	
— adjustable	Yes
S7 times	
Number	2 048
Retentivity	
— adjustable	Yes
IEC timer	
Number	Any (only limited by the main memory)
Retentivity	
— adjustable	Yes
Data areas and their retentivity	
Retentive data area (incl. timers, counters, flags), max.	128 kbyte; In total; available retentive memory for bit memories, timers, counters, DBs, and technology data (axes): 88 KB
Extended retentive data area (incl. timers, counters, flags), max.	1 Mbyte; When using PS 6 0W 24/48/60 V DC HF
Flag	
• Size, max.	16 kbyte
Number of clock memories	8; 8 clock memory bit, grouped into one clock memory byte
Data blocks	
 Retentivity adjustable 	Yes
Retentivity preset	No
Local data	
per priority class, max.	64 kbyte; max. 16 KB per block
Address area	
Number of IO modules	2 048; max. number of modules / submodules
I/O address area	
• Inputs	32 kbyte; All inputs are in the process image
Outputs	32 kbyte; All outputs are in the process image
per integrated IO subsystem	
— Inputs (volume)	8 kbyte
— Outputs (volume)	8 kbyte
per CM/CP	
— Inputs (volume)	8 kbyte
— Outputs (volume)	8 kbyte
Subprocess images	
Number of subprocess images, max.	32
Hardware configuration	
Number of distributed IO systems	32; A distributed I/O system is characterized not only by the integration of distributed I/O via PROFINET or PROFIBUS communication modules, but also by the connection of I/O via AS-i master modules or links (e.g. IE/PB-Link)
Number of DP masters	
Via CM Normalism of IO Controlling	6; A maximum of 6 CMs/CPs (PROFIBUS, PROFINET, Ethernet) can be inserted in total
Number of IO Controllers	
integratedVia CM	Research 1 A maximum of 6 CMs/CPs (PROFIBUS, PROFINET, Ethernet) can be inserted in total
Rack	
Modules per rack, max.	32; CPU + 31 modules
Number of lines, max.	1
PtP CM	
Number of PtP CMs	the number of connectable PtP CMs is only limited by the number of available slots
Time of day	
Clock	
• Type	Hardware clock
Backup time	6 wk; At 40 °C ambient temperature, typically
Deviation per day, max.	10 s; Typ.: 2 s
Operating hours counter	
Number	16

Clock synchronization	
supported	Yes
• in AS, master	Yes
• in AS, slave	Yes
 on Ethernet via NTP 	Yes
Digital inputs	
integrated channels (DI)	32
Digital inputs, parameterizable	Yes
Source/sink input	P-reading
Input characteristic curve in accordance with IEC 61131,	Yes
type 3	
Digital input functions, parameterizable	
Gate start/stop	Yes
Capture	Yes
 Synchronization 	Yes
Input voltage	
Type of input voltage	DC
Rated value (DC)	24 V
• for signal "0"	-3 to +5V
• for signal "1"	+11 to +30V
Input current	
• for signal "1", typ.	2.5 mA
Input delay (for rated value of input voltage)	
for standard inputs	
— parameterizable	Yes; none / 0.05 / 0.1 / 0.4 / 1.6 / 3.2 / 12.8 / 20 ms
— at "0" to "1", min.	4 μs; for parameterization "none"
— at "0" to "1", max.	20 ms
— at "1" to "0", min.	4 μs; for parameterization "none"
— at "1" to "0", max.	20 ms
	20 IIIS
for interrupt inputs	Vac. Carea as far standard inputs
— parameterizable	Yes; Same as for standard inputs
for technological functions	V 0 () 1 1 1
— parameterizable	Yes; Same as for standard inputs
Cable length	
• shielded, max.	1 000 m; 600 m for technological functions; depending on input frequency, encoder and cable quality; max. 50 m at 100 kHz
unshielded, max.	600 m; for technological functions: No
	000 III, IOI tecimological functions. No
Digital outputs	- ·
Type of digital output	Transistor
integrated channels (DO)	32
Current-sourcing	Yes; Push-pull output
Short-circuit protection	Yes; electronic/thermal
 Response threshold, typ. 	1.6 A with standard output, 0.5 A with high-speed output; see manual for
Limitation of industive abutdays valtage to	details Connector V11: 0.9 V: connector V12: L+ (52 V)
Limitation of inductive shutdown voltage to	Connector X11: -0.8 V; connector X12: L+ (-53 V)
Controlling a digital input	Yes
Accuracy of pulse duration	Up to ±100 ppm ±2 µs at high-speed output; see manual for details
minimum pulse duration	2 μs; With High Speed output
Digital output functions, parameterizable	V A 1 () 1 () 1 () 1
Switching tripped by comparison values	Yes; As output signal of a high-speed counter
PWM output	Yes
— Number, max.	4
 Cycle duration, parameterizable 	Yes
— ON period, min.	0 %
— ON period, max.	100 %
 Resolution of the duty cycle 	0.0036 %; For S7 analog format, min. 40 ns
Frequency output	Yes
Switching capacity of the outputs	
 with resistive load, max. 	0.5 A; 0.1 A with high-speed output, i.e. when using a high-speed
	output; see manual for details
 on lamp load, max. 	5 W; 1 W with high-speed output, i.e. when using a high-speed output;

	see manual for details
Load resistance range	
lower limit	48 Ω ; 240 ohms with high-speed output, i.e. when using a high-speed
	output; see manual for details
• upper limit	12 kΩ
Output voltage	
Type of output voltage	DC
• for signal "0", max.	1 V; With high-speed output, i.e. when using a high-speed output; see manual for details
• for signal "1", min.	23.2 V; L+ (-0.8 V)
Output current	20.2 V, L · (0.0 V)
• for signal "1" rated value	0.5 A; 0.1 A with high-speed output, i.e. when using a high-speed
To organia i ratou valuo	output, observe derating; see manual for details
for signal "1" permissible range, min.	2 mA
for signal "1" permissible range, max.	0.6 A; 0.12 A with high-speed output, i.e. when using a high-speed
	output, observe derating; see manual for details
• for signal "0" residual current, max.	0.5 mA
Output delay with resistive load	
• "0" to "1", max.	200 µs
• "1" to "0", max.	500 μs; Load-dependent
for technological functions	Euro Departing on the entertained and different transfer of
— "0" to "1", max.	5 µs; Depending on the output used, see additional description in manual
— "1" to "0". max.	5 µs; Depending on the output used, see additional description in
	manual
Parallel switching of two outputs	
 for logic links 	Yes; for technological functions: No
for uprating	No
for redundant control of a load	Yes; for technological functions: No
Switching frequency	
with resistive load, max.	100 kHz; For high-speed output, 100 Hz for standard output
 with inductive load, max. 	0.5 Hz; Acc. to IEC 60947-5-1, DC-13; observe derating curve
● on lamp load, max.	10 Hz
Total current of the outputs	
 Current per channel, max. 	0.5 A; see additional description in the manual
 Current per group, max. 	8 A; see additional description in the manual
Current per power supply, max.	4 A; 2 power supplies for each group, current per power supply max. 4 A, see additional description in manual
for technological functions	
— Current per channel, max.	0.5 A; see additional description in the manual
Relay outputs	
Number of relay outputs	0
Cable length	
• shielded, max.	1 000 m; 600 m for technological functions; depending on output frequency, load, and cable quality; max. 50 m at 100 kHz
• unshielded, max.	600 m; for technological functions: No
Analog inputs	
Number of analog inputs	5; 4x for U/I, 1x for R/RTD
 For current measurement 	4; max.
 For voltage measurement 	4; max.
For resistance/resistance thermometer measurement	1
permissible input voltage for voltage input (destruction limit), max.	28.8 V
permissible input current for current input (destruction limit), max.	40 mA
Cycle time (all channels), min.	1 ms; Dependent on the parameterized interference frequency suppression; for details, see conversion procedure in manual
Technical unit for temperature measurement adjustable	Yes; °C/°F/K
Input ranges (rated values), voltages	
• 0 to +10 V	Yes; Physical measuring range: ± 10 V
— Input resistance (0 to 10 V)	100 kΩ
• 1 V to 5 V	Yes; Physical measuring range: ± 10 V

— Input resistance (1 V to 5 V)	100 kΩ
- Input resistance (1 v to 5 v) • -10 V to +10 V	Yes
— Input resistance (-10 V to +10 V)	100 kΩ
• -5 V to +5 V	Yes; Physical measuring range: ± 10 V
— Input resistance (-5 V to +5 V)	100 k Ω
Input ranges (rated values), currents	100 K22
• 0 to 20 mA	Yes; Physical measuring range: ± 20 mA
— Input resistance (0 to 20 mA)	50 Ω ; Plus approx. 55 ohm for overvoltage protection by PTC
• -20 mA to +20 mA	Yes
— Input resistance (-20 mA to +20 mA)	50 Ω; Plus approx. 55 ohm for overvoltage protection by PTC
• 4 mA to 20 mA	Yes; Physical measuring range: ± 20 mA
— Input resistance (4 mA to 20 mA)	50 Ω; Plus approx. 55 ohm for overvoltage protection by PTC
Input ranges (rated values), resistance thermometer	
• Ni 100	Yes; Standard/climate
— Input resistance (Ni 100)	10 ΜΩ
• Pt 100	Yes; Standard/climate
— Input resistance (Pt 100)	10 ΜΩ
Input ranges (rated values), resistors	
• 0 to 150 ohms	Yes; Physical measuring range: 0 600 ohms
— Input resistance (0 to 150 ohms)	10 ΜΩ
• 0 to 300 ohms	Yes; Physical measuring range: 0 600 ohms
— Input resistance (0 to 300 ohms)	10 ΜΩ
• 0 to 600 ohms	Yes
— Input resistance (0 to 600 ohms)	10 ΜΩ
Cable length	
• shielded, max.	800 m; for U/I, 200 m for R/RTD
Analog outputs	
integrated channels (AO)	2
Voltage output, short-circuit protection	Yes
Cycle time (all channels), min.	1 ms; Dependent on the parameterized interference frequency suppression; for details, see conversion procedure in manual
Output ranges, voltage	suppression, for details, see softward of procedure in mandal
• 0 to 10 V	Yes
• 1 V to 5 V	Yes
• -10 V to +10 V	Yes
Output ranges, current	
• 0 to 20 mA	Yes
• -20 mA to +20 mA	Yes
• 4 mA to 20 mA	Yes
Load impedance (in rated range of output)	
with voltage outputs, min.	1 kΩ
 with voltage outputs, capacitive load, max. 	100 nF
with current outputs, max.	500 Ω
with current outputs, inductive load, max.	1 mH
Cable length	
• shielded, max.	200 m
Analog value generation for the inputs	
Integration and conversion time/resolution per channel	
 Resolution with overrange (bit including sign), max. 	16 bit
Integration time, parameterizable	Yes; 2.5 / 16.67 / 20 / 100 ms, acts on all channels
Interference voltage suppression for interference frequency f1 in H7.	400 / 60 / 50 / 10
frequency f1 in Hz Smoothing of measured values	
parameterizable	Yes
Step: None	Yes
• Step: None	Yes
• Step: Nedium	Yes
Step: High	Yes
Analog value generation for the outputs	
Integration and conversion time/resolution per channel	
integration and conversion time/resolution per channel	

- Decelution with everrange (bit including sign), may	16 hit
Resolution with overrange (bit including sign), max. Settling time.	16 bit
Settling time	1.5 mg
 for resistive load for capacitive load 	1.5 ms 2.5 ms
for inductive load	2.5 ms
Encoder	2.3 1118
Connection of signal encoders • for voltage measurement	Yes
for current measurement as 4-wire transducer	Yes
for resistance measurement with two-wire	Yes
connection	166
• for resistance measurement with three-wire	Yes
connection	
 for resistance measurement with four-wire connection 	Yes
Connectable encoders	
2-wire sensor	Yes
permissible quiescent current (2-wire sensor),	1.5 mA
max.	
Encoder signals, incremental encoder (asymmetrical)	
Input voltage	24 V
 Input frequency, max. 	100 kHz
Counting frequency, max.	400 kHz; with quadruple evaluation
Signal filter, parameterizable	Yes
 Incremental encoder with A/B tracks, 90° phase offset 	Yes
 Incremental encoder with A/B tracks, 90° phase offset and zero track 	Yes
• pulse encoder	Yes
 pulse encoder with direction 	Yes
 pulse encoder with one impulse signal per count 	Yes
direction	
Errors/accuracies	
Linearity error (relative to input range), (+/-)	0.1 %
Temperature error (relative to input range), (+/-)	0.005 %/K
Crosstalk between the inputs, max.	-60 dB - 0.05 %
Repeat accuracy in steady state at 25 °C (relative to input range), (+/-)	
Output ripple (relative to output range, bandwidth 0 to 50 kHz), (+/-)	0.02 %
kHz), (+/-) Linearity error (relative to output range), (+/-)	0.02 %
kHz), (+/-) Linearity error (relative to output range), (+/-) Temperature error (relative to output range), (+/-)	0.15 % 0.005 %/K
kHz), (+/-) Linearity error (relative to output range), (+/-) Temperature error (relative to output range), (+/-) Crosstalk between the outputs, max.	0.15 % 0.005 %/K -80 dB
kHz), (+/-) Linearity error (relative to output range), (+/-) Temperature error (relative to output range), (+/-)	0.15 % 0.005 %/K
kHz), (+/-) Linearity error (relative to output range), (+/-) Temperature error (relative to output range), (+/-) Crosstalk between the outputs, max. Repeat accuracy in steady state at 25 °C (relative to	0.15 % 0.005 %/K -80 dB
kHz), (+/-) Linearity error (relative to output range), (+/-) Temperature error (relative to output range), (+/-) Crosstalk between the outputs, max. Repeat accuracy in steady state at 25 °C (relative to output range), (+/-)	0.15 % 0.005 %/K -80 dB 0.05 %
kHz), (+/-) Linearity error (relative to output range), (+/-) Temperature error (relative to output range), (+/-) Crosstalk between the outputs, max. Repeat accuracy in steady state at 25 °C (relative to output range), (+/-) Operational error limit in overall temperature range	0.15 % 0.005 %/K -80 dB 0.05 % 0.3 % 0.3 %
kHz), (+/-) Linearity error (relative to output range), (+/-) Temperature error (relative to output range), (+/-) Crosstalk between the outputs, max. Repeat accuracy in steady state at 25 °C (relative to output range), (+/-) Operational error limit in overall temperature range • Voltage, relative to input range, (+/-) • Current, relative to input range, (+/-) • Resistance, relative to input range, (+/-)	0.15 % 0.005 %/K -80 dB 0.05 %
kHz), (+/-) Linearity error (relative to output range), (+/-) Temperature error (relative to output range), (+/-) Crosstalk between the outputs, max. Repeat accuracy in steady state at 25 °C (relative to output range), (+/-) Operational error limit in overall temperature range • Voltage, relative to input range, (+/-) • Current, relative to input range, (+/-)	0.15 % 0.005 %/K -80 dB 0.05 % 0.3 % 0.3 %
kHz), (+/-) Linearity error (relative to output range), (+/-) Temperature error (relative to output range), (+/-) Crosstalk between the outputs, max. Repeat accuracy in steady state at 25 °C (relative to output range), (+/-) Operational error limit in overall temperature range • Voltage, relative to input range, (+/-) • Current, relative to input range, (+/-) • Resistance, relative to input range, (+/-)	0.15 % 0.005 %/K -80 dB 0.05 % 0.3 % 0.3 % 0.3 % Pt100 Standard: ±2 K, Pt100 Climate: ±1 K, Ni100 Standard: ±1.2 K,
kHz), (+/-) Linearity error (relative to output range), (+/-) Temperature error (relative to output range), (+/-) Crosstalk between the outputs, max. Repeat accuracy in steady state at 25 °C (relative to output range), (+/-) Operational error limit in overall temperature range • Voltage, relative to input range, (+/-) • Current, relative to input range, (+/-) • Resistance, relative to input range, (+/-) • Resistance thermometer, relative to input range, (+/-) • Voltage, relative to output range, (+/-) • Current, relative to output range, (+/-)	0.15 % 0.005 %/K -80 dB 0.05 % 0.3 % 0.3 % 0.3 % Pt100 Standard: ±2 K, Pt100 Climate: ±1 K, Ni100 Standard: ±1.2 K, Ni100 Climate: ±1 K
kHz), (+/-) Linearity error (relative to output range), (+/-) Temperature error (relative to output range), (+/-) Crosstalk between the outputs, max. Repeat accuracy in steady state at 25 °C (relative to output range), (+/-) Operational error limit in overall temperature range • Voltage, relative to input range, (+/-) • Current, relative to input range, (+/-) • Resistance, relative to input range, (+/-) • Resistance thermometer, relative to input range, (+/-) • Voltage, relative to output range, (+/-) • Current, relative to output range, (+/-) • Current, relative to output range, (+/-)	0.15 % 0.005 %/K -80 dB 0.05 % 0.3 % 0.3 % Pt100 Standard: ±2 K, Pt100 Climate: ±1 K, Ni100 Standard: ±1.2 K, Ni100 Climate: ±1 K 0.3 % 0.3 %
kHz), (+/-) Linearity error (relative to output range), (+/-) Temperature error (relative to output range), (+/-) Crosstalk between the outputs, max. Repeat accuracy in steady state at 25 °C (relative to output range), (+/-) Operational error limit in overall temperature range • Voltage, relative to input range, (+/-) • Current, relative to input range, (+/-) • Resistance, relative to input range, (+/-) • Resistance thermometer, relative to input range, (+/-) • Voltage, relative to output range, (+/-) • Current, relative to output range, (+/-) Basic error limit (operational limit at 25 °C) • Voltage, relative to input range, (+/-)	0.15 % 0.005 %/K -80 dB 0.05 % 0.3 % 0.3 % Pt100 Standard: ±2 K, Pt100 Climate: ±1 K, Ni100 Standard: ±1.2 K, Ni100 Climate: ±1 K 0.3 % 0.3 % 0.3 % 0.2 %
kHz), (+/-) Linearity error (relative to output range), (+/-) Temperature error (relative to output range), (+/-) Crosstalk between the outputs, max. Repeat accuracy in steady state at 25 °C (relative to output range), (+/-) Operational error limit in overall temperature range • Voltage, relative to input range, (+/-) • Resistance, relative to input range, (+/-) • Resistance thermometer, relative to input range, (+/-) • Voltage, relative to output range, (+/-) • Current, relative to output range, (+/-) • Current, relative to input range, (+/-)	0.15 % 0.005 %/K -80 dB 0.05 % 0.3 % 0.3 % 0.3 % Pt100 Standard: ±2 K, Pt100 Climate: ±1 K, Ni100 Standard: ±1.2 K, Ni100 Climate: ±1 K 0.3 % 0.3 % 0.2 % 0.2 %
kHz), (+/-) Linearity error (relative to output range), (+/-) Temperature error (relative to output range), (+/-) Crosstalk between the outputs, max. Repeat accuracy in steady state at 25 °C (relative to output range), (+/-) Operational error limit in overall temperature range • Voltage, relative to input range, (+/-) • Current, relative to input range, (+/-) • Resistance, relative to input range, (+/-) • Resistance thermometer, relative to input range, (+/-) • Current, relative to output range, (+/-) • Current, relative to output range, (+/-) Basic error limit (operational limit at 25 °C) • Voltage, relative to input range, (+/-) • Current, relative to input range, (+/-) • Resistance, relative to input range, (+/-)	0.15 % 0.005 %/K -80 dB 0.05 % 0.3 % 0.3 % Pt100 Standard: ±2 K, Pt100 Climate: ±1 K, Ni100 Standard: ±1.2 K, Ni100 Climate: ±1 K 0.3 % 0.3 % 0.3 % 0.2 % 0.2 % 0.2 %
kHz), (+/-) Linearity error (relative to output range), (+/-) Temperature error (relative to output range), (+/-) Crosstalk between the outputs, max. Repeat accuracy in steady state at 25 °C (relative to output range), (+/-) Operational error limit in overall temperature range • Voltage, relative to input range, (+/-) • Resistance, relative to input range, (+/-) • Resistance thermometer, relative to input range, (+/-) • Voltage, relative to output range, (+/-) • Current, relative to output range, (+/-) • Current, relative to input range, (+/-)	0.15 % 0.005 %/K -80 dB 0.05 % 0.3 % 0.3 % 0.3 % Pt100 Standard: ±2 K, Pt100 Climate: ±1 K, Ni100 Standard: ±1.2 K, Ni100 Climate: ±1 K 0.3 % 0.3 % 0.2 % 0.2 % Pt100 Standard: ±1 K, Pt100 Climate: ±0.5 K, Ni100 Standard: ±0.6 K,
kHz), (+/-) Linearity error (relative to output range), (+/-) Temperature error (relative to output range), (+/-) Crosstalk between the outputs, max. Repeat accuracy in steady state at 25 °C (relative to output range), (+/-) Operational error limit in overall temperature range • Voltage, relative to input range, (+/-) • Current, relative to input range, (+/-) • Resistance, relative to input range, (+/-) • Resistance thermometer, relative to input range, (+/-) • Voltage, relative to output range, (+/-) • Current, relative to output range, (+/-) • Current, relative to input range, (+/-) • Current, relative to input range, (+/-) • Resistance, relative to input range, (+/-) • Resistance, relative to input range, (+/-) • Resistance thermometer, relative to input range, (+/-)	0.15 % 0.005 %/K -80 dB 0.05 % 0.3 % 0.3 % Pt100 Standard: ±2 K, Pt100 Climate: ±1 K, Ni100 Standard: ±1.2 K, Ni100 Climate: ±1 K 0.3 % 0.3 % 0.2 % 0.2 % Pt100 Standard: ±1 K, Pt100 Climate: ±0.5 K, Ni100 Standard: ±0.6 K, Ni100 Climate: ±0.5 K
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kHz), (+/-) Linearity error (relative to output range), (+/-) Temperature error (relative to output range), (+/-) Crosstalk between the outputs, max. Repeat accuracy in steady state at 25 °C (relative to output range), (+/-) Operational error limit in overall temperature range • Voltage, relative to input range, (+/-) • Resistance, relative to input range, (+/-) • Resistance thermometer, relative to input range, (+/-) • Voltage, relative to output range, (+/-) • Current, relative to output range, (+/-) • Current, relative to output range, (+/-) • Current, relative to input range, (+/-) • Resistance, relative to input range, (+/-) • Resistance, relative to input range, (+/-) • Resistance thermometer, relative to input range, (+/-) • Resistance thermometer, relative to input range, (+/-) • Current, relative to output range, (+/-) • Current, relative to output range, (+/-)	0.15 % 0.005 %/K -80 dB 0.05 % 0.3 % 0.3 % Pt100 Standard: ±2 K, Pt100 Climate: ±1 K, Ni100 Standard: ±1.2 K, Ni100 Climate: ±1 K 0.3 % 0.3 % 0.2 % 0.2 % 0.2 % Pt100 Standard: ±1 K, Pt100 Climate: ±0.5 K, Ni100 Standard: ±0.6 K, Ni100 Climate: ±0.5 K
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interference < rated value of input range), min.	
 Common mode voltage, max. 	10 V
Common mode interference, min.	60 dB; at 400 Hz: 50 dB
Interfaces	
Number of PROFINET interfaces	1
1. Interface	
Interface types	
RJ 45 (Ethernet)	Yes; X1
 Number of ports 	2
integrated switch	Yes
Protocols	
IP protocol	Yes; IPv4
 PROFINET IO Controller 	Yes
 PROFINET IO Device 	Yes
 SIMATIC communication 	Yes
Open IE communication	Yes; Optionally also encrypted
Web server	Yes
Media redundancy	Yes
PROFINET IO Controller	
Services	
— PG/OP communication	Yes
— Isochronous mode	Yes
Direct data exchange	Yes; Requirement: IRT and isochronous mode (MRPD optional)
— IRT	Yes
— PROFlenergy	Yes; per user program
— Prioritized startup	Yes; Max. 32 PROFINET devices
 Number of connectable IO Devices, max. 	128; In total, up to 256 distributed I/O devices can be connected via AS-i, PROFIBUS or PROFINET
 Of which IO devices with IRT, max. 	64
Number of connectable IO Devices for RT,	128
max.	120
— of which in line, max.	128
 Number of IO Devices that can be 	8; in total across all interfaces
simultaneously activated/deactivated, max.	
 Number of IO Devices per tool, max. 	8
Updating times	The minimum value of the update time also depends on communication
	share set for PROFINET IO, on the number of IO devices, and on the quantity of configured user data
Update time for IRT	
— for send cycle of 250 μs	250 µs to 4 ms; Note: In the case of IRT with isochronous mode, the
	minimum update time of 625 µs of the isochronous OB is decisive
— for send cycle of 500 μs	500 µs to 8 ms; Note: In the case of IRT with isochronous mode, the
	minimum update time of 625 μs of the isochronous OB is decisive
— for send cycle of 1 ms	1 ms to 16 ms
— for send cycle of 2 ms	2 ms to 32 ms
— for send cycle of 4 ms	4 ms to 64 ms
 With IRT and parameterization of "odd" send cycles 	Update time = set "odd" send clock (any multiple of 125 μs: 375 μs, 625 μs 3 875 μs)
Update time for RT	μο σ σ, σ μο)
— for send cycle of 250 μs	250 µs to 128 ms
— for send cycle of 500 μs	500 µs to 256 ms
— for send cycle of 1 ms	1 ms to 512 ms
— for send cycle of 2 ms	2 ms to 512 ms
— for send cycle of 4 ms	4 ms to 512 ms
PROFINET IO Device	
Services	
— PG/OP communication	Yes
Isochronous mode	No
— IRT	Yes
— PROFlenergy	Yes; per user program
— Shared device	Yes
Number of IO Controllers with shared device,	4

max.	
 activation/deactivation of I-devices 	Yes; per user program
Asset management record	Yes; per user program
Interface types	
RJ 45 (Ethernet)	
• 100 Mbps	Yes
 Autonegotiation 	Yes
 Autocrossing 	Yes
Industrial Ethernet status LED	Yes
Protocols	
Number of connections	
Number of connections, max.	128; via integrated interfaces of the CPU and connected CPs / CMs
Number of connections reserved for ES/HMI/web	10
Number of connections via integrated interfaces	88
Number of S7 routing paths	16
Redundancy mode	v
H-Sync forwarding	Yes
Media redundancy	only via 1et interface (V1)
— Media redundancy	only via 1st interface (X1)
— MRP	Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP Manager; MRP Client
 MRP interconnection, supported 	Yes; as MRP ring node according to IEC 62439-2 Edition 3.0
— MRPD	Yes; Requirement: IRT
 Switchover time on line break, typ. 	200 ms; For MRP, bumpless for MRPD
Number of stations in the ring, max.	50
SIMATIC communication	
PG/OP communication	Yes; encryption with TLS V1.3 pre-selected
S7 routing	Yes
 S7 communication, as server 	Yes
 S7 communication, as client 	Yes
 User data per job, max. 	See online help (S7 communication, user data size)
Open IE communication	
• TCP/IP	Yes
— Data length, max.	64 kbyte
 several passive connections per port, 	Yes
supported	v.
• ISO-on-TCP (RFC1006)	Yes
— Data length, max.	64 kbyte
UDP Data langth, may	Yes
— Data length, max.	2 kbyte; 1 472 bytes for UDP broadcast
— UDP multicast	Yes; Max. 5 multicast circuits
• DHCP	Yes Yes
DNS SNMP	Yes
SNMP DCP	Yes
• DCP • LLDP	Yes Yes
Encryption	Yes; Optional
Web server	100, Optional
• HTTP	Yes; Standard and user pages
• HTTPS	Yes; Standard and user pages
OPC UA	
Runtime license required	Yes; "Small" license required
OPC UA Client	Yes
Application authentication	Yes
— Security policies	Available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256
 User authentication 	"anonymous" or by user name & password
User authenticationNumber of connections, max.	"anonymous" or by user name & password 4
 Number of connections, max. 	4 1 000 300

max. — Number of elements for one call of	20
OPC_UA_NameSpaceGetIndexList, max.	20
 Number of elements for one call of OPC_UA_MethodGetHandleList, max. 	100
 Number of simultaneous calls of the client instructions per connection (except OPC_UA_ReadList,OPC_UA_WriteList,OPC_UA_M max. 	1
 Number of simultaneous calls of the client instructions OPC_UA_ReadList,OPC_UA_WriteList and 	5
OPC_UA_MethodCall, max.	
 Number of registerable nodes, max. 	5 000
 Number of registerable method calls of OPC_UA_MethodCall, max. 	100
 Number of inputs/outputs when calling OPC_UA_MethodCall, max. 	20
OPC UA Server	Yes; Data access (read, write, subscribe), method call, custom address space
 Application authentication 	Yes
— Security policies	Available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256
 User authentication 	"anonymous" or by user name & password
 — GDS support (certificate management) 	Yes
 Number of sessions, max. 	32
 Number of accessible variables, max. 	50 000
 Number of registerable nodes, max. 	10 000
 Number of subscriptions per session, max. 	20
— Sampling interval, min.	100 ms
— Publishing interval, min.	500 ms
 Number of server methods, max. 	20
 Number of inputs/outputs per server method, 	20
max.	20
 Number of monitored items, max. 	1 000; for 1 s sampling interval and 1 s send interval
— Number of server interfaces, max.	10 of each "Server interfaces" / "Companion specification" type and 20 of the type "Reference namespace"
 Number of nodes for user-defined server interfaces, max. 	1 000
 Alarms and Conditions 	Yes
 Number of program alarms 	100
Number of alarms for system diagnostics	50
Further protocols	
MODBUS	Yes; MODBUS TCP
Isochronous mode	
Equidistance	Yes
S7 message functions	1.50
	32
Number of login stations for message functions, max.	
Program alarms Number of configurable program messages, max.	Yes 5 000; Program messages are generated by the "Program_Alarm"
Number of leadable program massages in DUM, may	block, ProDiag or GRAPH 2 500
Number of loadable program messages in RUN, max.	2 000
Number of simultaneously active program alarms	600
Number of program alarms Number of alarms for system diagnostics.	600
Number of plarms for system diagnostics Number of plarms for motion technology chicate	100
Number of alarms for motion technology objects	80
Test commissioning functions	
Joint commission (Team Engineering)	Yes; Parallel online access possible for up to 5 engineering systems
Status block	Yes; Up to 8 simultaneously (in total across all ES clients)
Single step	No
Number of breakpoints	8
Status/control Status/control variable	Yes

 Variables 	Inputs/outputs, memory bits, DBs, distributed I/Os, timers, counters
 Number of variables, max. 	
— of which status variables, max.	200; per job
— of which control variables, max.	200; per job
Forcing	
• Forcing	Yes
• Forcing, variables	Peripheral inputs/outputs
Number of variables, max.	200
Diagnostic buffer	
• present	Yes
 Number of entries, max. 	1 000
— of which powerfail-proof	500
Traces	
Number of configurable Traces	4; Up to 512 KB of data per trace are possible
Interrupts/diagnostics/status information	
Alarms	
Diagnostic alarm	Yes
Hardware interrupt	Yes
Diagnoses	V
 Monitoring the supply voltage 	Yes
• Wire-break	Yes; for analog inputs/outputs, see description in manual
Short-circuit	Yes; for analog outputs, see description in manual
A/B transition error at incremental encoder	Yes
Diagnostics indication LED	
RUN/STOP LED	Yes
• ERROR LED	Yes
MAINT LED	Yes
STOP ACTIVE LED	Yes
 Monitoring of the supply voltage (PWR-LED) 	Yes
 Channel status display 	Yes
• for channel diagnostics	Yes; For analog inputs/outputs
for channel diagnosticsConnection display LINK TX/RX	Yes; For analog inputs/outputs Yes
 for channel diagnostics Connection display LINK TX/RX Supported technology objects	Yes
for channel diagnosticsConnection display LINK TX/RX	
for channel diagnostics Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for	Yes; Note: The number of technology objects affects the cycle time of
for channel diagnostics Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool
for channel diagnostics Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool
 for channel diagnostics Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis 	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800
 for channel diagnostics Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis 	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 80
for channel diagnostics Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 80 160
for channel diagnostics Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80
 for channel diagnostics Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam 	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20
for channel diagnostics Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80
 for channel diagnostics Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam per cam track per probe 	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20
for channel diagnostics Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160
 for channel diagnostics Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) 	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160
 for channel diagnostics Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Positioning axis Number of positioning axes at motion control 	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40
for channel diagnostics Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40
for channel diagnostics Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40 5 10 Yes; Universal PID controller with integrated optimization
for channel diagnostics Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Sstep	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40 5 10 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves
for channel diagnostics Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40 5 10 Yes; Universal PID controller with integrated optimization
for channel diagnostics Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Temp Counting and measuring	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature
for channel diagnostics Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Step PID-Temp Counting and measuring High-speed counter	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40 5 10 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves
for channel diagnostics Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Temp Counting and measuring	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature
for channel diagnostics Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Temp Counting and measuring High-speed counter Integrated Functions Counter	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature
for channel diagnostics Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Temp Counting and measuring High-speed counter Integrated Functions Counter Number of counters	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 800 40 80 160 80 20 160 40 5 10 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature Yes
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 Continuous counting 	Yes
 Counter response parameterizable 	Yes
 Hardware gate via digital input 	Yes
Software gate	Yes
 Event-controlled stop 	Yes
 Synchronization via digital input 	Yes
Counting range, parameterizable	Yes
Comparator	
 Number of comparators 	2; per count channel; see manual for details
 Direction dependency 	Yes
— Can be changed from user program	Yes
Position detection	
 Incremental acquisition 	Yes
 Suitable for S7-1500 Motion Control 	Yes
Measuring functions	
 Measuring time, parameterizable 	Yes
 Dynamic measurement period adjustment 	Yes
 Number of thresholds, parameterizable 	2
Measuring range	
Frequency measurement, min.	0.04 Hz
— Frequency measurement, max.	400 kHz; with quadruple evaluation
Cycle duration measurement, min.	2.5 µs
Cycle duration measurement, max.	25 s
Accuracy	
Frequency measurement	100 ppm; depending on measuring interval and signal evaluation
Cycle duration measurement	100 ppm; depending on measuring interval and signal evaluation
Velocity measurement	100 ppm; depending on measuring interval and signal evaluation
Potential separation	Too ppin, depending on medading interval and dignal evaluation
Potential separation digital inputs • between the channels	Mo
	No
between the channels, in groups of Petertial acceptate distribute states.	16
Potential separation digital outputs	All
between the channels	No
between the channels, in groups of	16
Potential separation channels	
between the channels and backplane bus	Yes
Between the channels and load voltage L+	No
Isolation	
Isolation tested with	707 V DC (type test)
Ambient conditions	
Ambient temperature during operation	
 horizontal installation, min. 	-25 °C; No condensation
 horizontal installation, max. 	60 °C; note derating data for onboard I/O in the manual. Display: 50 °C,
	at an operating temperature of typically 50 °C, the display is switched off
 vertical installation, min. 	-25 °C; No condensation
 vertical installation, max. 	40 °C; note derating data for onboard I/O in the manual. Display: 40 °C,
	at an operating temperature of typically 40 °C, the display is switched off
Ambient temperature during storage/transportation	
● min.	-40 °C
• max.	70 °C
Altitude during operation relating to sea level	
Installation altitude above sea level, max.	5 000 m; Restrictions for installation altitudes > 2 000 m, see manual
configuration / header	
configuration / programming / header	
Programming language	
— LAD	Yes
— FBD	Yes
— STL	Yes
— SCL	Yes
— GRAPH	Yes
	

Know-how protection	
User program protection/password protection	Yes
 Copy protection 	Yes
 Block protection 	Yes
Access protection	
 protection of confidential configuration data 	Yes
 Password for display 	Yes
 Protection level: Write protection 	Yes
 Protection level: Read/write protection 	Yes
Protection level: Complete protection	Yes
programming / cycle time monitoring / header	
 lower limit 	adjustable minimum cycle time
• upper limit	adjustable maximum cycle time
Dimensions	
Width	110 mm
Height	147 mm
Depth	129 mm
Weights	
Weight, approx.	1 360 g

11/3/2021

last modified: