Data sheet

6ES7518-4FP00-0AB0



SIMATIC S7-1500F, CPU 1518F-4 PN/DP, central processing unit with 9 MB work memory for program and 60 MB for data, 1st interface: PROFINET IRT with 2-port switch, 2nd interface: PROFINET RT, 3rd interface: PROFINET basic services, 4th interface: PROFIBUS, 1 ns bit-performance, SIMATIC Memory Card required

General information	
Product type designation	CPU 1518F-4PN/DP
HW functional status	FS10
Firmware version	V2.9
Product function	
• I&M data	Yes; I&M0 to I&M3
Isochronous mode	Yes; Distributed and central; with minimum OB $6x$ cycle of $125~\mu s$ (distributed) and $1~ms$ (central)
Engineering with	
 STEP 7 TIA Portal configurable/integrated from version 	V17 (FW V2.9) / V13 (FW V1.5) or higher
Configuration control	
via dataset	Yes
Display	
Screen diagonal [cm]	6.1 cm
Control elements	
Number of keys	6
Mode selector switch	1
Supply voltage	
Type of supply voltage	DC
Rated value (DC)	24 V
permissible range, lower limit (DC)	19.2 V
permissible range, upper limit (DC)	28.8 V
Reverse polarity protection	Yes
Mains buffering	
 Mains/voltage failure stored energy time 	5 ms
Repeat rate, min.	1/s
Input current	
Current consumption (rated value)	1.55 A
Inrush current, max.	2.4 A; Rated value
l²t	0.02 A ² ·s
Power	
Infeed power to the backplane bus	12 W
Power consumption from the backplane bus (balanced)	30 W
Power loss	
Power loss, typ.	24 W
Memory	
Number of slots for SIMATIC memory card	1
SIMATIC memory card required	Yes

Mark manager	
Work memory	O Mbyto
• integrated (for program)	9 Mbyte
• integrated (for data)	60 Mbyte
Load memory	00.01
Plug-in (SIMATIC Memory Card), max.	32 Gbyte
Backup	Vos
maintenance-free	Yes
CPU processing times	
for bit operations, typ.	1 ns
for word operations, typ.	2 ns
for fixed point arithmetic, typ.	2 ns
for floating point arithmetic, typ.	6 ns
CPU-blocks	00.000 PL L (OR ER EQ PR) LURT
Number of elements (total)	20 000; Blocks (OB, FB, FC, DB) and UDTs
DB	4 00 000
Number range	1 60 999; subdivided into: number range that can be used by the user: 1 59 999, and number range of DBs created via SFC 86: 60 000 60 999
• Size, max.	16 Mbyte; For DBs with absolute addressing, the max. size is 64 KB
FB	
Number range	0 65 535
• Size, max.	1 Mbyte
FC	
Number range	0 65 535
• Size, max.	1 Mbyte
ОВ	
• Size, max.	1 Mbyte
 Number of free cycle OBs 	100
 Number of time alarm OBs 	20
 Number of delay alarm OBs 	20
 Number of cyclic interrupt OBs 	20; with minimum OB 3x cycle of 100 μs
 Number of process alarm OBs 	50
 Number of DPV1 alarm OBs 	3
 Number of isochronous mode OBs 	3
 Number of technology synchronous alarm OBs 	2
 Number of startup OBs 	100
 Number of asynchronous error OBs 	4
 Number of synchronous error OBs 	2
Number of diagnostic alarm OBs	1
Nesting depth	
per priority class	24
Counters, timers and their retentivity	
S7 counter	
Number	2 048
Retentivity	
— adjustable	Yes
IEC counter	
Number	Any (only limited by the main memory)
Retentivity	
— adjustable	Yes
S7 times	
• Number	2 048
Retentivity	V
— adjustable	Yes
IEC timer	
• Number	Any (only limited by the main memory)
Retentivity	W
— adjustable	Yes
Data areas and their retentivity	
Retentive data area (incl. timers, counters, flags), max.	768 kbyte; In total; available retentive memory for bit memories, timers,

	counters DRs and technology data (avea): 700 KB
Extended retentive data area (incl. timers, counters, flags),	counters, DBs, and technology data (axes): 700 KB 20 Mbyte; When using PS 6 0W 24/48/60 V DC HF
max.	20 Mbyte, When daing F3 0 0W 24/40/00 V DC Til
Flag	
• Size, max.	16 kbyte
 Number of clock memories 	8; 8 clock memory bit, grouped into one clock memory byte
Data blocks	
Retentivity adjustable	Yes
Retentivity preset	No
Local data	
 per priority class, max. 	64 kbyte; max. 16 KB per block
Address area	
Number of IO modules	16 384; max. number of modules / submodules
I/O address area	
• Inputs	32 kbyte; All inputs are in the process image
Outputs	32 kbyte; All outputs are in the process image
per integrated IO subsystem	
— Inputs (volume)	32 kbyte; max. 32 KB via X1; max. 8 KB via X2 or X4
— Outputs (volume)	32 kbyte; max. 32 KB via X1; max. 8 KB via X2 or X4
per CM/CP	
— Inputs (volume)	8 kbyte
— Outputs (volume)	8 kbyte
Subprocess images	
Number of subprocess images, max.	32
lardware configuration	
Number of distributed IO systems	64; A distributed I/O system is characterized not only by the integration
Trainibal of distribution to Systems	of distributed I/O via PROFINET or PROFIBUS communication modules, but also by the connection of I/O via AS-i master modules or links (e.g. IE/PB-Link)
Number of DP masters	
integrated	1
• Via CM	8; A maximum of 8 CMs/CPs (PROFIBUS, PROFINET, Ethernet) can be inserted in total
Number of IO Controllers	
integrated	2
• Via CM	8; A maximum of 8 CMs/CPs (PROFIBUS, PROFINET, Ethernet) can
Dook	be inserted in total
Rack	00. ODIL + 04
Modules per rack, max.	32; CPU + 31 modules
Number of lines, max.	1
PtP CM	
Number of PtP CMs	the number of connectable PtP CMs is only limited by the number of available slots
ime of day	available diote
Clock	Hardware clock
Type Packup time	Hardware clock
Backup time Deviation per day, may	6 wk; At 40 °C ambient temperature, typically
Deviation per day, max. Operating bours accepted.	10 s; Typ.: 2 s
Operating hours counter	10
Number Clask an absorbation	16
Clock synchronization	V
• supported	Yes
• to DP, master	Yes
• in AS, master	Yes
• in AS, slave	Yes
on Ethernet via NTP	Yes
nterfaces	
Number of PROFINET interfaces	3
Number of PROFIBUS interfaces	1
. Interface	
Interface types	

D145 (5)	V V4
RJ 45 (Ethernet)	Yes; X1
Number of ports	2
integrated switch	Yes
Protocols	V 1D 4
IP protocol	Yes; IPv4
PROFINET IO Controller	Yes
PROFINET IO Device	Yes
SIMATIC communication	Yes
Open IE communication	Yes; Optionally also encrypted
Web server	Yes
Media redundancy	Yes; MRP Automanager according to IEC 62439-2 Edition 2.0
PROFINET IO Controller	
Services	V
— PG/OP communication	Yes
— Isochronous mode	Yes
— Direct data exchange	Yes; Requirement: IRT and isochronous mode (MRPD optional)
— IRT	Yes
— PROFlenergy	Yes; per user program
— Prioritized startup	Yes; Max. 32 PROFINET devices
Number of connectable IO Devices, max.	512; In total, up to 1 000 distributed I/O devices can be connected via AS-i, PROFIBUS or PROFINET
— Of which IO devices with IRT, max.	64
 Number of connectable IO Devices for RT, max. 	512
— of which in line, max.	512
Number of IO Devices that can be simultaneously activated/deactivated, max.	8; in total across all interfaces
 Number of IO Devices per tool, max. 	8
— Updating times	The minimum value of the update time also depends on communication share set for PROFINET IO, on the number of IO devices, and on the quantity of configured user data
Update time for IRT	
— for send cycle of 125 μs	125 µs
— for send cycle of 187.5 μs	187.5 μs
— for send cycle of 250 μs	250 µs to 4 ms
— for send cycle of 500 μs	500 µs to 8 ms
— for send cycle of 1 ms	1 ms to 16 ms
— for send cycle of 2 ms	2 ms to 32 ms
— for send cycle of 4 ms	4 ms to 64 ms
 With IRT and parameterization of "odd" send cycles 	Update time = set "odd" send clock (any multiple of 125 μ s: 375 μ s, 625 μ s 3 875 μ s)
Update time for RT	
— for send cycle of 250 µs	250 µs to 128 ms
— for send cycle of 500 μs	500 µs to 256 ms
— for send cycle of 1 ms	1 ms to 512 ms
— for send cycle of 2 ms	2 ms to 512 ms
— for send cycle of 4 ms	4 ms to 512 ms
PROFINET IO Device	
Services	
— PG/OP communication	Yes
— Isochronous mode	No
— IRT	Yes; Minimum send cycle of 250 µs
— PROFlenergy	Yes; per user program
— Shared device	Yes
 Number of IO Controllers with shared device, max. 	4
 activation/deactivation of I-devices 	Yes; per user program
 Asset management record 	Yes; per user program
. Interface	
Interface types	
RJ 45 (Ethernet)	Yes; X2
 Number of ports 	1

integrated switch	No
Protocols	
IP protocol	Yes; IPv4
PROFINET IO Controller	Yes
PROFINET IO Device	Yes
SIMATIC communication	Yes
Open IE communication	Yes; Optionally also encrypted
Web server	Yes
Media redundancy	No
PROFINET IO Controller	
Services	
— PG/OP communication	Yes
— Isochronous mode	No
— Direct data exchange	No
— IRT	No
— PROFlenergy	Yes; per user program
— Prioritized startup	No
— Number of connectable IO Devices, max.	128; In total, up to 1 000 distributed I/O devices can be connected via AS-i, PROFIBUS or PROFINET
 Number of connectable IO Devices for RT, max. 	128
— of which in line, max.	128
Number of IO Devices that can be	8; in total across all interfaces
simultaneously activated/deactivated, max.	
 Number of IO Devices per tool, max. 	8
— Updating times	The minimum value of the update time also depends on communication share set for PROFINET IO, on the number of IO devices, and on the
Hadata fina far DT	quantity of configured user data
Update time for RT	4 ma to 540 ma
— for send cycle of 1 ms	1 ms to 512 ms
PROFINET IO Device	
Services — PG/OP communication	Von
Isochronous mode	Yes
— ISOCITIONOUS Mode — IRT	No No
	No Vacanta and an analysis
— PROFlenergy	Yes; per user program
— Prioritized startup	No V
— Shared device	Yes
 Number of IO Controllers with shared device, max. 	4
activation/deactivation of I-devices	Yes; per user program
Asset management record	Yes; per user program
3. Interface	, 400.
Interface types	
• RJ 45 (Ethernet)	Yes; X3
Number of ports	1
• integrated switch	No
Protocols	
IP protocol	Yes; IPv4
PROFINET IO Controller	No
PROFINET IO Device	No
SIMATIC communication	Yes
Open IE communication	Yes
Web server	Yes
Web server 4. Interface	160
Interface types	Voc. V4
• RS 485	Yes; X4
 Number of ports 	1
Protocols	V
Protocols PROFIBUS DP master PROFIBUS DP slave	Yes No

SIMATIC communication	Yes
PROFIBUS DP master	
Number of connections, max.	48; for the integrated PROFIBUS DP interface
Number of DP slaves, max.	125; In total, up to 1 000 distributed I/O devices can be connected via AS-i, PROFIBUS or PROFINET
Services	
— PG/OP communication	Yes
— Equidistance	Yes
 Isochronous mode 	Yes
 Activation/deactivation of DP slaves 	Yes
Interface types	
RJ 45 (Ethernet)	
• 100 Mbps	Yes
• 1000 Mbps	Yes; Only possible at the X3 interface of the CPU 1518
Autonegotiation	Yes
Autocrossing	Yes
Industrial Ethernet status LED	Yes
RS 485	
Transmission rate, max.	12 Mbit/s
Protocols	
PROFIsafe	Yes; V2.4 / V2.6
Number of connections	
Number of connections, max.	384; via integrated interfaces of the CPU and connected CPs / CMs
Number of connections reserved for ES/HMI/web	10
Number of connections via integrated interfaces	320
Number of S7 routing paths	64; in total, only 16 S7-Routing connections are supported via
- Training parts	PROFIBUS
Redundancy mode	
H-Sync forwarding	Yes
Media redundancy	
 Media redundancy 	only via 1st interface (X1)
— MRP	Yes; as MRP redundancy manager and/or MRP client
 MRP interconnection, supported 	Yes; as ring node according to IEC 62439-2 Edition 2.0
— MRPD	Yes; Requirement: IRT
 Switchover time on line break, typ. 	200 ms; For MRP, bumpless for MRPD
Number of stations in the ring, max.	50
SIMATIC communication	
 S7 routing 	Yes
Data record routing	Yes
 S7 communication, as server 	Yes
 S7 communication, as client 	Yes
User data per job, max.	See online help (S7 communication, user data size)
Open IE communication	
• TCP/IP	Yes
— Data length, max.	64 kbyte
 several passive connections per port, supported 	Yes
• ISO-on-TCP (RFC1006)	Yes
— Data length, max.	64 kbyte
• UDP	Yes
— Data length, max.	2 kbyte; 1 472 bytes for UDP broadcast
— UDP multicast	Yes; 128 multicast circuits (of which max. 5 via X1)
• DHCP	Yes
• DNS	Yes
• SNMP	Yes
• DCP	Yes
• LLDP	Yes
Encryption	Yes; Optional
Web server	
• HTTP	Yes; Standard and user pages
• HTTPS	Yes: Standard and user pages

ODC IIA	
OPC UA • Puntime license required	Voc
Runtime license required ORC HA Client	Yes
OPC UA Client Application purchasetisetism	Yes
— Application authentication	Yes
— Security policies	Available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256
 User authentication 	"anonymous" or by user name & password
 Number of connections, max. 	40
 Number of nodes of the client interfaces, max. 	5 000
 Number of elements for one call of OPC_UA_NodeGetHandleList/OPC_UA_ReadList/C max. 	300
 Number of elements for one call of OPC_UA_NameSpaceGetIndexList, max. 	20
 Number of elements for one call of OPC_UA_MethodGetHandleList, max. 	100
 Number of simultaneous calls of the client instructions per connection (except OPC_UA_ReadList,OPC_UA_WriteList,OPC_UA_M max. 	1
 Number of simultaneous calls of the client 	5
instructions OPC_UA_ReadList,OPC_UA_WriteList and OPC_UA_MethodCall, max.	
Number of registerable nodes, max.	5 000
Number of registerable method calls of OPC_UA_MethodCall, max.	100
Number of inputs/outputs when calling OPC_UA_MethodCall, max.	20
OPC UA Server	Yes; Data access (read, write, subscribe), method call, custom address space
 Application authentication 	Yes
— Security policies	Available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256
 User authentication 	"anonymous" or by user name & password
Number of sessions, max.	64
 Number of accessible variables, max. 	200 000
 Number of registerable nodes, max. 	50 000
 Number of subscriptions per session, max. 	20
 — Sampling interval, min. 	10 ms
— Publishing interval, min.	10 ms
 Number of server methods, max. 	100
 Number of inputs/outputs per server method, max. 	20
 Number of monitored items, max. 	10 000; for 1 s sampling interval and 1 s send interval
 Number of server interfaces, max. 	10 of each "Server interfaces" / "Companion specification" type and 20 of the type "Reference namespace"
 Number of nodes for user-defined server interfaces, max. 	30 000
 Alarms and Conditions 	
 Number of program alarms 	400
Number of alarms for system diagnostics	200
Further protocols	
• MODBUS	Yes; MODBUS TCP
Isochronous mode	
Equidistance	Yes
S7 message functions	
Number of login stations for message functions, max.	64
manipor or login stations for incodage fulletions, max.	
Program alarms	Yes
	Yes 10 000; Program messages are generated by the "Program_Alarm" block, ProDiag or GRAPH
Program alarms	10 000; Program messages are generated by the "Program_Alarm"
Program alarms Number of configurable program messages, max.	10 000; Program messages are generated by the "Program_Alarm" block, ProDiag or GRAPH

• Number of alarms for avotem diagnostics	1,000
Number of alarms for system diagnostics Number of alarms for motion technology objects.	1 000
Number of alarms for motion technology objects Test commissioning functions	480
Test commissioning functions	Voca Parallal anlina access ressible for up to 40 anning and
Joint commission (Team Engineering)	Yes; Parallel online access possible for up to 10 engineering systems
Status block	Yes; Up to 16 simultaneously (in total across all ES clients)
Single step	No
Number of breakpoints Status/control	20
Status/control variable	Yes; without fail-safe
Variables	inputs/outputs, bit memories, DBs, peripheral I/Os (without fail-safe),
Valiables	times, counters
 Number of variables, max. 	
— of which status variables, max.	200; per job
— of which control variables, max.	200; per job
Forcing	
Forcing	Yes; without fail-safe
 Forcing, variables 	peripheral inputs/outputs (without fail-safe)
 Number of variables, max. 	200
Diagnostic buffer	
• present	Yes
 Number of entries, max. 	3 200
— of which powerfail-proof	1 000
Traces	
Number of configurable Traces	8; Up to 512 KB of data per trace are possible
Interrupts/diagnostics/status information	
Diagnostics indication LED	
RUN/STOP LED	Yes
• ERROR LED	Yes
MAINT LED	Yes
 Connection display LINK TX/RX 	Yes
Supported technology objects	
Motion Control	Yes; Note: The number of technology objects affects the cycle time of
	the PLC program; selection guide via the TIA Selection Tool
 Number of available Motion Control resources for 	15 360
technology objects	
Paguired Motion Control recourses	
Required Motion Control resources	
— per speed-controlled axis	40
per speed-controlled axisper positioning axis	80
per speed-controlled axisper positioning axisper synchronous axis	80 160
per speed-controlled axisper positioning axisper synchronous axisper external encoder	80 160 80
 per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam 	80 160 80 20
 per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam per cam track 	80 160 80 20 160
 per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam 	80 160 80 20
 per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Positioning axis 	80 160 80 20 160 40
 per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Positioning axis Number of positioning axes at motion control 	80 160 80 20 160
 per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) 	80 160 80 20 160 40
 per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) Number of positioning axes at motion control 	80 160 80 20 160 40
 per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) Number of positioning axes at motion control cycle of 8 ms (typical value) 	80 160 80 20 160 40
 per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) Number of positioning axes at motion control cycle of 8 ms (typical value) 	80 160 80 20 160 40 140
— per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe • Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller • PID_Compact	80 160 80 20 160 40 140 192 Yes; Universal PID controller with integrated optimization
 per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_3Step 	80 160 80 20 160 40 140 192 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves
— per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe • Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller • PID_Compact • PID_Step • PID-Temp	80 160 80 20 160 40 140 192 Yes; Universal PID controller with integrated optimization
 per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_3Step PID-Temp Counting and measuring	80 160 80 20 160 40 140 192 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves
 per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_3Step PID-Temp Counting and measuring High-speed counter 	80 160 80 20 160 40 140 192 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature
 per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_3Step PID-Temp Counting and measuring High-speed counter Standards, approvals, certificates	80 160 80 20 160 40 140 192 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature
 per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_3Step PID-Temp Counting and measuring High-speed counter Standards, approvals, certificates Highest safety class achievable in safety mode	80 160 80 20 160 40 140 192 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature Yes
 per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_3Step PID-Temp Counting and measuring High-speed counter Standards, approvals, certificates Highest safety class achievable in safety mode Performance level according to ISO 13849-1 	80 160 80 20 160 40 140 192 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature Yes
— per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe • Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller • PID_Compact • PID_Sstep • PID-Temp Counting and measuring • High-speed counter Standards, approvals, certificates Highest safety class achievable in safety mode • Performance level according to ISO 13849-1 • SIL acc. to IEC 61508	80 160 80 20 160 40 140 192 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature Yes PLe SIL 3
— per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe • Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller • PID_Compact • PID_Step • PID-Temp Counting and measuring • High-speed counter Standards, approvals, certificates Highest safety class achievable in safety mode • Performance level according to ISO 13849-1 • SIL acc. to IEC 61508 Probability of failure (for service life of 20 years and rep	80 160 80 20 160 40 140 192 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature Yes PLe SIL 3 pair time of 100 hours)
— per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe • Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller • PID_Compact • PID_Step • PID-Temp Counting and measuring • High-speed counter Standards, approvals, certificates Highest safety class achievable in safety mode • Performance level according to ISO 13849-1 • SIL acc. to IEC 61508	80 20 160 40 140 192 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature Yes PLe SIL 3

— High demand/continuous mode: PFH in	< 1.00E-09
accordance with SIL3	
Ambient conditions	
Ambient temperature during operation	
 horizontal installation, min. 	0 °C
 horizontal installation, max. 	60 °C; Display: 50 °C, at an operating temperature of typically 50 °C, the display is switched off
 vertical installation, min. 	0 °C
vertical installation, max.	40 °C; Display: 40 °C, at an operating temperature of typically 40 °C, the display is switched off
Ambient temperature during storage/transportation	
• min.	-40 °C
• max.	70 °C
Altitude during operation relating to sea level	
 Installation altitude above sea level, max. 	5 000 m; Restrictions for installation altitudes > 2 000 m, see manual
configuration / header	
configuration / programming / header	
Programming language	
— LAD	Yes; incl. failsafe
— FBD	Yes; incl. failsafe
— STL	Yes
— SCL	Yes
— GRAPH	Yes
Know-how protection	
 User program protection/password protection 	Yes
 Copy protection 	Yes
Block protection	Yes
Access protection	
 Password for display 	Yes
 Protection level: Write protection 	Yes; Specific write protection both for Standard and for Failsafe
 Protection level: Read/write protection 	Yes
 Protection level: Write protection for Failsafe 	Yes
Protection level: Complete protection	Yes
programming / cycle time monitoring / header	
 lower limit 	adjustable minimum cycle time
• upper limit	adjustable maximum cycle time
Dimensions	
Width	175 mm
Height	147 mm
Depth	129 mm
Weights	
Weight, approx.	1 988 g

last modified: 11/3/2021 ☑